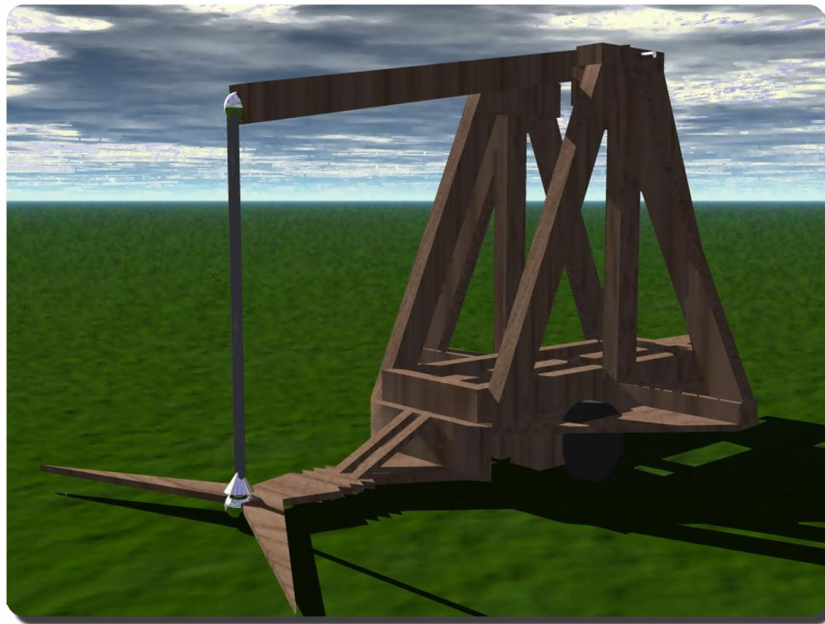


# Mr. T



An Autonomous Trebuchet

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## **Abstract**

Mr. T (short for Mr. Trebuchet) is an autonomous robotic trebuchet designed to find and throw ammunition at a target at least 10 yards away. It will continue to hurl objects until turned off. There is also a logical boundary that Mr. T will travel within. This boundary is the maximum and minimum distances the objects can be thrown. Mr. T will know his exact position and angle at all times, and can determine how far he is from the target.

## **Executive Summary**

Mr. T is a modern version of one of the most powerful and devastating siege engines ever used. A trebuchet is similar to a catapult, but instead of using tension to launch an object, a trebuchet uses a pivot arm, a sling, and a massive counterweight to hurl the object over great distances.

The main purpose of Mr. T is to lay siege on a castle, positioned about 10 yards away from the robot. He will drive around semi-randomly, searching for appropriate objects to throw (specially designed ammunition) that can be thrown. Once ammunition is found, it is loaded onto an electromagnetic sling and hurled at the target. The round is released from the trebuchet at an optimum time for a direct hit on a target. By adjusting release times, Mr. T can compensate for being different distances from the target.

In order to stay aware of his body and the environment around him, Mr. T uses four types of sensors. These include IR sensors, bump sensors, potentiometers, and a special vector processing unit that can determine, through the use of an optical mouse, the exact position and angle the robot is facing.

The hardware used includes two Motorola HC11 EVBU boards with the Mekatronix ME11 memory and port expansion, a mouse, a AWCE PAK-VI, a UART, and several resistors, capacitor, transistors, and relays.

## **Introduction**

The trebuchet was first introduced into western society by the Greeks or Romans in the 12<sup>th</sup> century, but was mostly developed during the middle ages by the French. Originating at around 300 B.C. in China, the trebuchet became one of the most popular and devastating siege engines during the middle ages. Characterized by its massive counterweight and long sling, trebuchets could throw heavy rocks and other objects (often dead horses or peasants infected with the plague) over hundreds of yards with amazing accuracy. Because trebuchets use a weight – counterweight design, it does not rely on tension like a catapult. This means that if you load ammunition with nearly the same weight every time, the trebuchet will throw it in the exact location.

Little has changed in trebuchet design in the last 500 years. The Hobbyists that compete in pumpkin throwing contests construct nearly the same devices that were used in the middle ages. My goal was to create a robot that merged state of the art processors and sensors with tried and true medieval weaponry to create an autonomous siege engine. Through this, Mr. T was created.

Mr. T is the first trebuchet that has a mind of its own. The only conditions it needs to work is for it to be a known distance away from and angle in relation to the target. It then searches its surrounding area for ammunition, loads that ammunition, and then launches it at the target. It has the intelligence to know where it is at all times (including angle and position), so an accurate, direct hit can be thrown every time.

## **Integrated System**

Mr. T is a multiprocessor based robotic trebuchet. Its system can be broken down into several categories. Some of these are the hardware used, as well as the behaviors it can perform, and the sensors used. This hardware can perform all of the functions required of the robot

### ***Hardware***

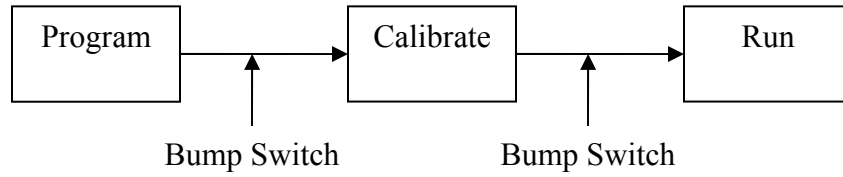
Mr. T is based on two Motorola 68HC11 evaluation boards each equipped with a Motorola MC68HC11E9 processor and the Mekatronix ME11 memory and port expansion board. The robot uses two NiCad battery packs to provide energy, as well as one 12 V Lead Acid battery which provides energy for the on board electromagnet. A system of random searching was used by the robot to find the ammunition, 32 bit precision floating point vector calculations to find its current location, as well as floating point calculations to find the target.

### ***Sensors and Additional Hardware***

Sensors in the device included a mouse, two IR transmitter / receivers, a potentiometer, and a bump switch. An AWCE PAK-VI, a National Semiconductor UART, and an Eriez EM-R1 small flat faced electromagnet were some additional hardware that was required. The connections to the device included two parallel port interfaces, an AC adapter plug, and several switches and buttons.

### ***Behaviors***

Mr. T has three main modes of operation. These modes are programming, calibration, and running. The running mode can be broken down into several smaller modes; searching, loading, returning, aiming, and firing. Also, during running mode the device is constantly performing obstacle avoidance.



*Figure 1 - Behaviors*

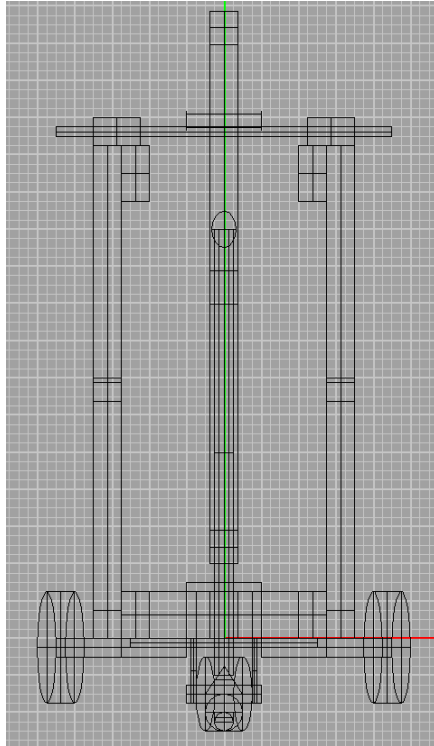
## **Mobile Platform**

The mobile platform needed not only to be able to withstand the large amount of force generated by the throwing arm, but to also be able to be maneuvered accurately. The platform can be divided into several sections: the platform, the arm and pivot, the wheels, the catcher, sling, and the weight crate.

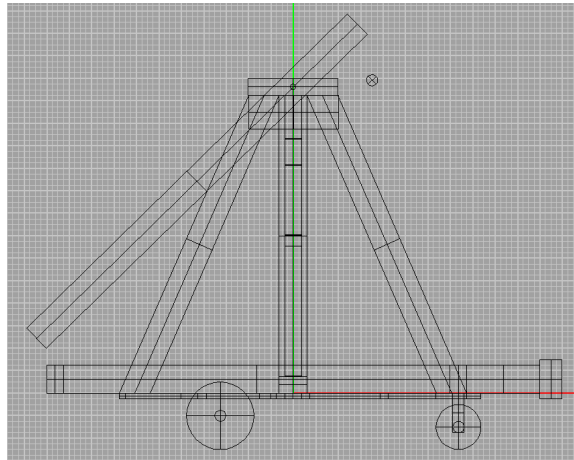
### ***Platform***

To make the platform strong enough to survive the force laid upon it, 1" x 2" pine wood was used instead of the conventional airline plywood. To connect all of the pieces of wood together, #8 wood screws were used along with two supporting nails. The final, reinforced design was the third attempt at making the structure. The first implementation used larger wood and was a little too large for what was needed. The second design used the same size wood as my final implementation, but was built without reinforcing nails and with larger screws. The structure could not handle the weight of the test throws and began to lose stability quickly. The final design, shown below in figure 2, was created without the side reinforcements which were not being used. See appendix A for scaled representations of the beams required.





*Figure 2a – Front View*

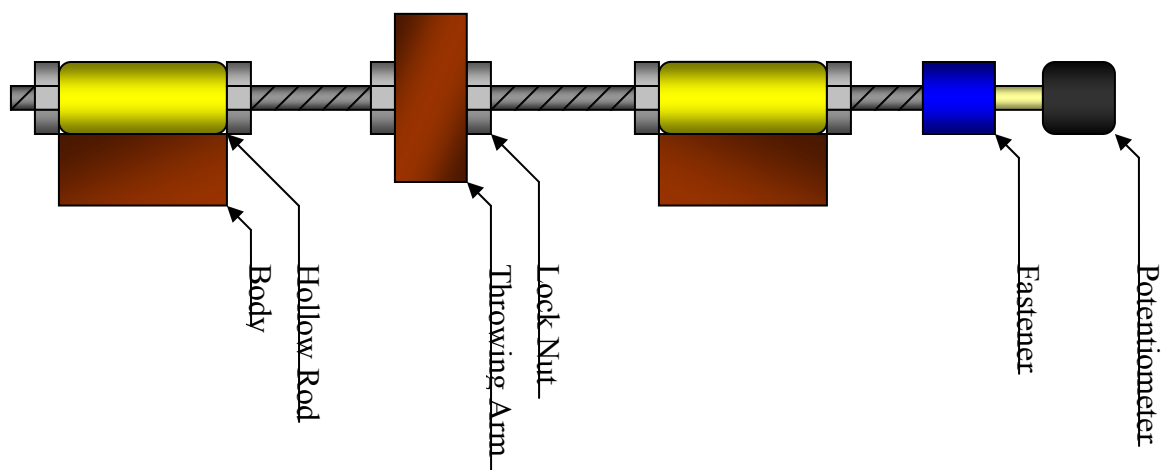


*Figure 2b – Side View*

### ***Arm and Pivot***

The arm was constructed with the same size wood as the body. The arm was 25" in length. At a point  $\frac{1}{2}$ " in on both sides a hole was drilled. There was also a larger whole drilled in  $4 \frac{1}{2}$ " from the end of the short side.

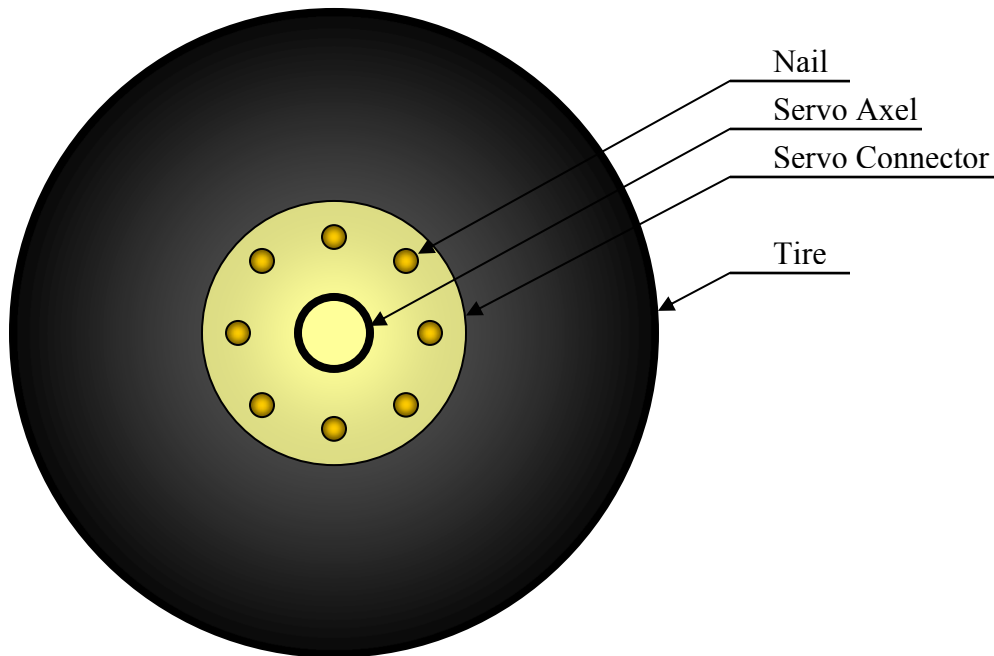
The pivot used was a ¼" threaded rod. Two ½" hollow metal tubes were used where the arm connects to the body. First, the two tubes were attached to the wood with strong epoxy, and then secured with metal strips that were screwed into the surface. Next, the rod was placed through the tube with the lock nut configuration shown in figure 3. The nuts around the tube were loosely secured, while the two nuts holding the wooden arm were secured as tightly as possible. The goal of this was to make the rod and the arm turn together, while having causing as little rotational friction as possible with the body. The rod needed to always turn with the arm because the rod is then connected to a potentiometer (with at least a 270° range of motion) for determining the position of the arm at all times.



*Figure 3 – Arm and Pivot*

## ***Wheels***

For the wheels, three 4" tires with supports were used. These can be found at any hardware store. For the drive wheel, the tire was removed from the axel and secured to the large round servo connector. This was secured by drilling eight small holes into the all rubber tire and then hammering in small nails to connect it. Because of the nature of rubber, when the nails were hammered in, it stretches the rubber which then holds them tightly in place. Figure 4 shows how the tire is connected.

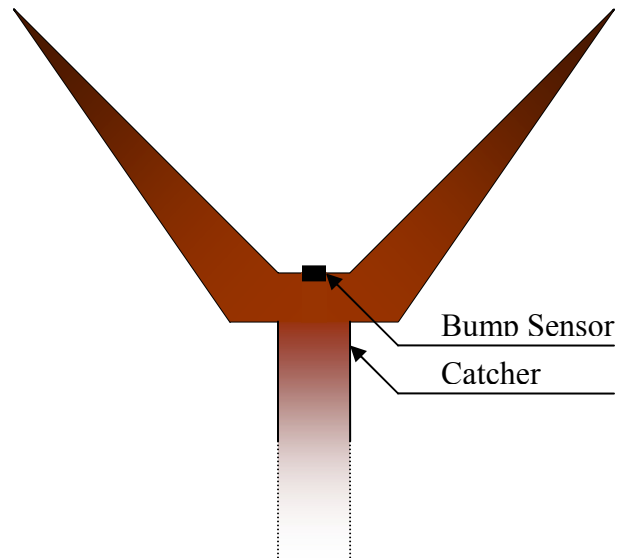


*Figure 4 – Tire Connection*

## ***Catcher***

The purpose of the catcher is to catch the ammunition as the robot moves towards it, and position the ammunition so that when the arm lowers to the “load” position the magnet is resting upon it. The easiest way to do this was to create a “V” shaped aircraft plywood

structure, with the widest point of the “V” the same width as the tires. The bottom of the “V” is about the width of the ammunition (1”), and there is a bump sensor there to tell the robot when the ammunition is properly placed. This section is shown in figure 4.



*Figure 4 – Catcher*

### ***Sling***

The sling consists of the electromagnet, and a 13" piece of picture wire, as well as a #10 screw. The end of the wire is inserted into the hole in the back of the electromagnet, and a #10 screw is screwed in. This fastens the wire to the magnet. The other end of the wire is threaded through the arm and secured by either a knot or some other method (fastener, solder, etc.).

### ***Weight Crate***

The final piece of the platform is the weight crate. This is essentially a box that surrounds the 12 Volt lead-acid battery. It needs to be very strong, or the battery will fly out of the bottom, and it also must be able to let the battery be removed. In addition to this, it needs to minimize the sideways swing so that when it moves it will not strike the sides of the body. It also must be able to swing freely forwards and backwards to properly transfer its energy. In building testing, the box was destroyed several times. Because of this, the final version of the box is reinforced with metal sheets, and made to be almost the exact size of the battery (to minimize that movement of the battery in the crate). This piece is shown below in figure 5.

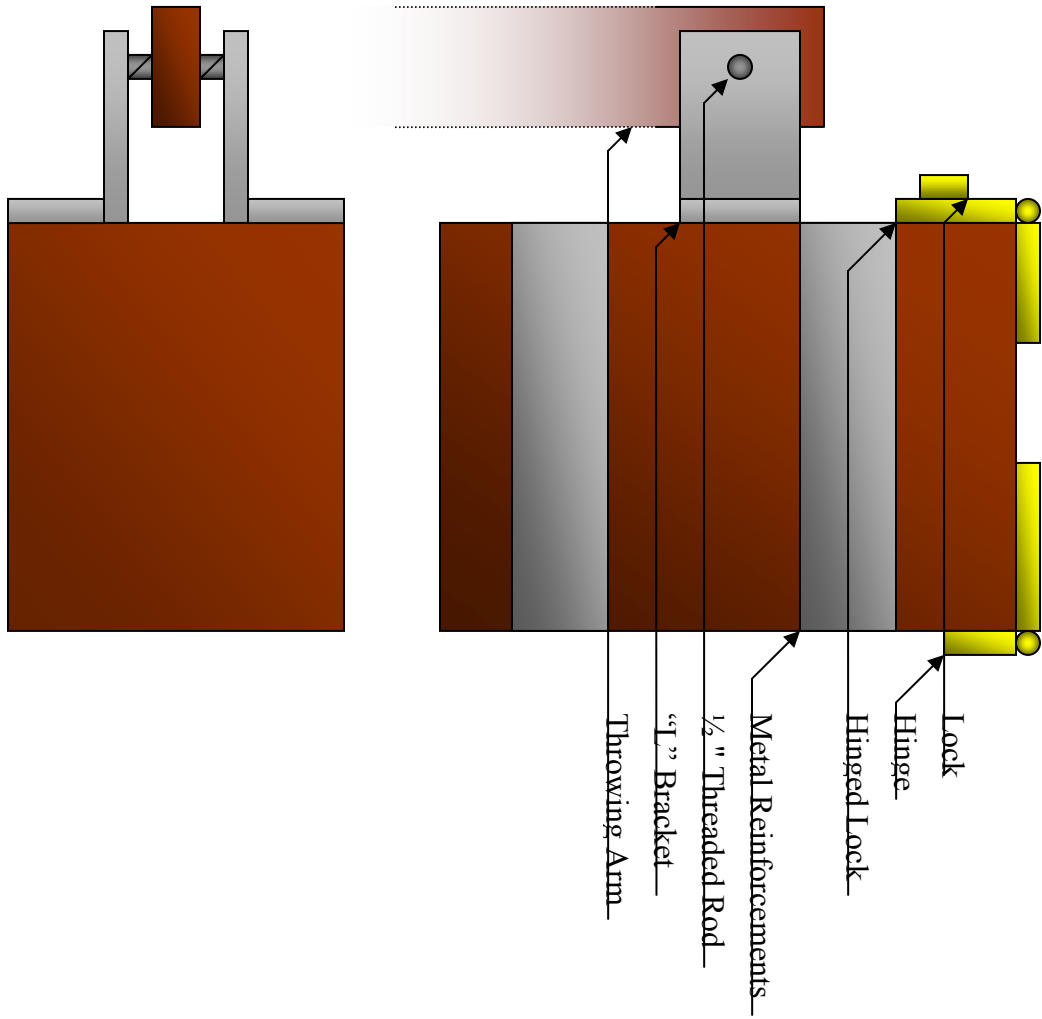


Figure 5 – Weight Crate

## **Actuation**

The only actuation devices used for the robot were four servos. These were used for four tasks; steering, driving, winching, and locking. The same system calls were used to work all of the servos. The value in the A register is decimal 0, 50, or 100. When it is 50, the servo turns to the neutral position (or off if hacked), when it 100 is entered, the servo will rotate to  $+90^\circ$  (or continuously rotate clockwise), and if 0 is entered the servo will rotate to  $-90^\circ$  (or counter clockwise). The code for this can be found in appendix B.

## ***Steering***

The same wheel was used for both steering and driving. This was to make it easier for the robot to travel in a straight line and to pivot around a single point. The servo used for steering was a Cirrus CS-80. The CS-80 is a metal geared, two ball bearing high torque servo. At 6 Volts (the voltage it is used at), the CS-80 has 129.86 oz-in. of torque, and the speed is .25 sec/ $60^\circ$ . The steering servo of robot is only needed to go to  $0^\circ$ ,  $90^\circ$ , and  $-90^\circ$ . This servo was not hacked.

## ***Drive***

The drive servo is massive. Because so much weight must be moved, the servo chosen was the Cirrus CS-600 FET. This servo can produce a huge 333.29 oz-in. of torque at 6 Volts. Its speed is .22 sec/ $60^\circ$ . The drive servo was hacked so it can continuously go forwards or backwards.

### ***Winch***

The winch needed to be strong enough to lift the 6 lbs counterweight while moving the arm to the loading and arming position. This servo was a hacked version of the CS-80. It has the same specifications as the steering servo.

### ***Lock***

The lock servo is used to hold the arm in place while the winch releases the wire. This is needed because the winch would otherwise produce too much rotational friction in the arm and it would waste too much energy. This servo does not need to be very powerful, so a smaller Cirrus CS-60 was used. The speed of this servo is .14 sec/60°, and the torque is 56.38 oz-in.



## **Sensors**

Four different sensors were used in the design of Mr. T.: a bump sensor, Infrared Range Detectors, a potentiometer, and a special vector processing unit.

### ***Bump Sensor***

Since only one bump sensor was used, it was connected in a simple voltage divider circuit to one of the analog ports. If the button was depressed the analog port read about 2.5 V, and if it was not pressed the port would read about 0 V.

### ***Infrared Range Detector***

The Infrared sensor used was the Sharp GP2DI2. This is a 40 kHz transmitter and receiver combined into one. The inputs to it are ground, +5 V, and it outputs an analog signal that represents the range from an object. The IR sensors are situated with one above the other so that if an object is detected on the lower IR but not the upper IR, than it is ammunition.

### ***Potentiometer***

The third sensor used was also very straight forward. The potentiometer attached to the pivot of the arm is connected to a voltage divider circuit. The value received by the analog port represents exactly where the arm is at any time. The potentiometer used had a range of 0 – 10 k $\Omega$ . When placed in series with another 10 k $\Omega$  resistor, the values read to the analog port ranged from 5 V – 2.5 V, and the circuit did not draw too much amperage to function properly. Initially lower resistor values were used, but too much current was trying to be drawn, and it drained the batteries too quickly.

## ***Vector Processing Unit***

The vector processing was a special sensor designed specifically for Mr. T. Appendix C shows all of the code written for the VPU.

### **Function**

The main function of the sensor is to give an accurate position measurement, including angle, based on an initial position.

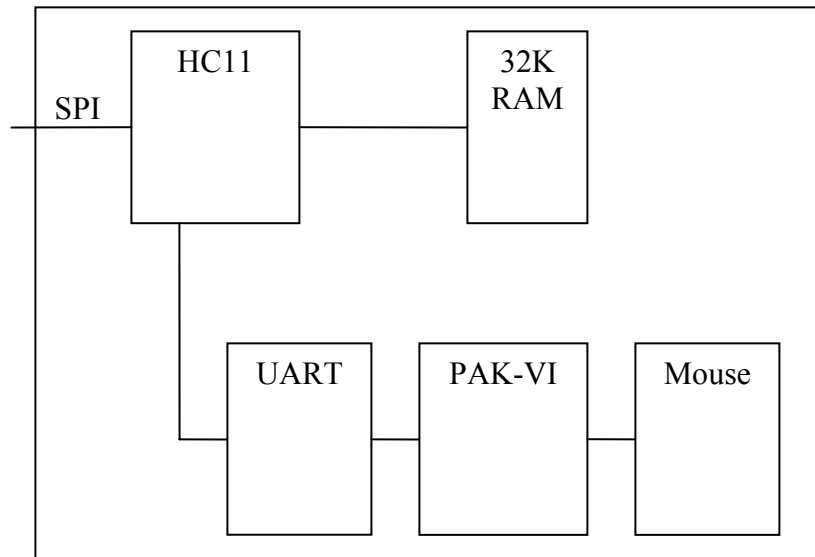
### **Guidelines**

The sensor had several important guidelines to make it useful. The most important one was that it must have a very small error. This is important for two main reasons. Since the device is going to sample many times per second and the same numbers are going to be used (because current location is always a function of previous location), any small error will continue to be compounded and make the later results very inaccurate. The other main reason is that since the target is so far away, any inaccuracies will be multiplied by this distance and make the final calculation off.

### **Implementation**

To implement this, the robot uses an optical mouse and a dedicated 68HC11. Mr. T samples the mouse every 10 ms, and computes the calculations with the value returned.

Figure 6 shows the block structure of this sensor.



*Figure 6 – Block Diagram*

The intention is to make the sensor a “black box” device with a small instruction set. The only way the main processor of the robot can communicate with it is through the SPI interface. The instruction set is shown in figure 7.

Instruction	Opcode	Input	Output
Get X	\$01		float XAbsolute
Get Y	\$02		float YAbsolute
Get Theta	\$03		float ThetaAbsolute
Start Mouse	\$04		
Stop Mouse	\$05		
Reset Mouse Counter	\$06		
Reset Angle	\$07		
Compute distance	\$08	float XTarget, YTarget	int Distance

*Figure 7 – Instruction Set of Vector Processing Unit*

The PAK-VI is a keyboard controller that can also be used as an all purpose PS/2 controller. There is an instruction that you can send it that passes the next byte of data directly to the PS/2 port. This function was used to put the mouse into remote mode. Remote mode is a method where instead of the mouse constantly streaming data to the PS/2 port, it only reports data when requested. The data it returns is three 8 bit values. From these values two 9 bit values representing changes in X and Y positions can be extracted. These values are then put through the mathematical calculations shown in figure 8. All calculations are done as 32 bit floating point numbers.

$$\begin{aligned}\Delta X &= \text{Sampled X} \\ \Delta Y &= \text{Sampled Y} \\ R &= \text{Radius from mouse to wheels} \\ \Delta\Theta &= \frac{\Delta X}{R} \\ \Theta &= \Theta + \Delta\Theta \\ X &= \Delta Y \cdot \cos(\Theta) + X \\ Y &= \Delta Y \cdot \sin(\Theta) + Y\end{aligned}$$

*Figure 9 – Mathematical Vector Calculations*

## **Errors**

This sensor was never fully functional. The calculations simulated correctly, but the interface between the HC11 and the UART never worked properly. Because of this, no data concerning the accuracy of the sensor has yet to be created.

## **Behaviors**

Mr. T has three main modes of operation. These modes are program, calibrate, and run.

### ***Programming***

In this mode, the robot remains stationary as new code is loaded into its memory. This mode is the initial mode the robot is in

### ***Calibrate***

In the calibration mode, the robot calibrates its sensor values for the room it is in. It should be placed 12" from a piece of ammunition, and 20" from the wall. It will then calibrate the IR. The pushbutton is pressed to confirm it is in the correct location. Since many problems were found with navigation, this mode has yet to be implemented.

### ***Run***

During the entire run mode, the robot is performing obstacle avoidance. The run mode can be broken down into five smaller modes: searching, loading, returning, aiming, and firing. The code for this mode can be found in appendix D.

### **Searching**

In the searching mode, the robot is looking for ammunition. It starts out by rotating around in a circle, all the while checking the IR sensors for any objects. If an object is detected in the lower IR but not the upper, than the robot drives towards it. This object will be a piece of ammunition. If nothing is detected, or an obstacle is detected, it travels in a random direction away from the object. It continues to do this until an object is found. When it drives towards a piece of ammunition, it continues to drive forward until

the bump switch is depressed, meaning an object is in the ready position. Once this happens, the mode changes to the loading state.

### **Loading**

When the robot is ready to load, it begins to winch down the arm. It continues to do this while checking the position of arm until the arm reaches a predetermined “loading” position. Once in the loading position, the electromagnet is turned on. After the electromagnet, the robot changes to arming mode.

### **Arming**

When arming, the robot winches the arm down more while slowly moving away from the target. This causes the sling to slide under the robot. It again checks the arms position. Once the armed position is found, the lock is lowered and the winch is unwound for a predetermined amount of time.

### **Aiming**

When aiming, the robot first turns its steering wheel to 90°, and then revolves until the vector processing unit says that it is pointed directly at the target. Once it is aimed at the target, the vector processing unit is queried for the position to release the ammunition for it to strike the target. Once this position is found, the robot emits a warning sound and counts down with an LED display for 5 seconds and then moves to the fire state.

### **Firing**

In the fire state, the robot stops all other calculations and spends all of its time sampling the analog port. As soon as the value determined in the aiming state is found, the magnet

is released and the target flies towards its target. After this, the robot returns to the searching state.

## **Experimental Results**

The robot is not yet function enough to acquire proper experimental results. This section will be updated when the robot becomes functional.



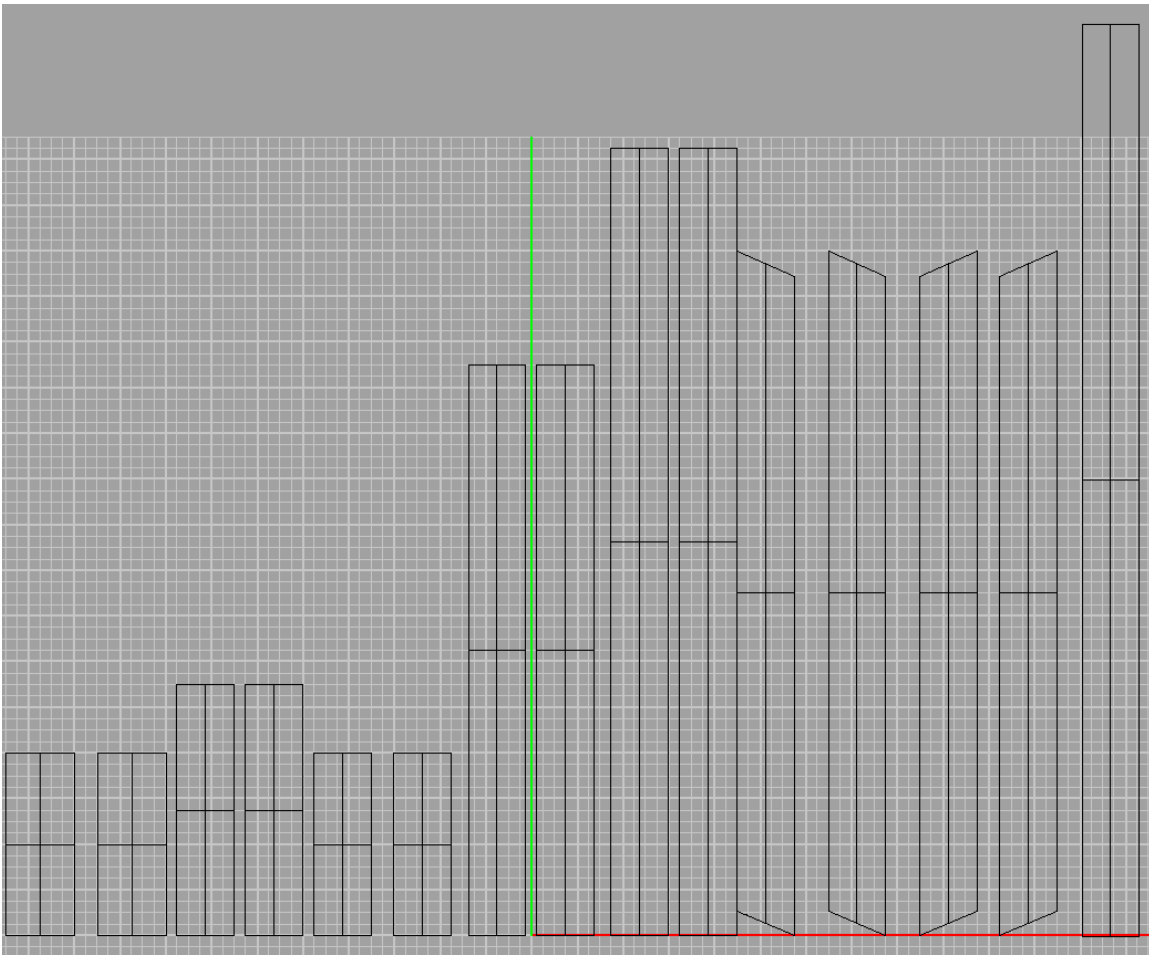
## **Conclusion**

Although countless hours were spent in working on this robot, it has yet to do much of anything. I am still working on it, and it will be mostly functional soon, but at this point it does not work.

Many of my problems came from problems with hardware. It took me a very long time to discover that one of the ME11 boards I am using might not be working properly. Whenever my servos change direction or stop it resets my board. This even happens when the servos are on independent power supplies. I was also having problems with my UART. I can not check to see if my mouse sensor works correctly because the serial interface does not work.

I plan on finishing this project in the near future. I am very frustrated that it does not work correctly, and hope to have it fully functional soon.

## Appendix A – Scale Drawing



Scale – 1 square = 1/4"

## Appendix B – Servo Code

```
*****  
* INIT INTERRUPT VECTORS *  
*****
```

```
ORG    $00D3  
JMP    HANDLE_OC5  
JMP    HANDLE_OC4  
JMP    HANDLE_OC3  
JMP    HANDLE_OC2
```

```
ORG    $8000  
LDX    #BASE  
CLRA  
STAA   TMSK2,X  
LDAA   #%01111000  
STAA   TMSK1,X  
STAA   TFLG1,X  
CLI
```

```
*****  
* WINCH IN THE ARM *  
*****
```

```
LDAA   #0  
JSR    S_WINCH  
  
LOWER JSR    GET_ARM  
LDAB   #$4F  
CBA  
  
BEQ    LOWER_DONE  
BRA    LOWER  
  
LOWER_DONE  
LDAA   #50  
JSR    S_WINCH
```

```
here bra here
```

```
*****  
* DRIVE SERVO *  
*****
```

```
ORG    $9000  
S_DRIVE LDAB #50  
CBA  
BGT    DR_CW  
BLT    DR_CCW  
  
LDAA   #$0B  
STAA   $02
```

```

RTS

DR_CW LDAA  #\$04
      STAA  \$02
      RTS

DR_CCW      LDAA  #\$14
      STAA  \$02
      RTS

```

```

*****
* TURNING SERVO *
*****

```

```

      ORG  \$9100
S_TURN      LDAB  #50
      CBA
      BGT  TN_CW
      BLT  TN_CCW

      LDAA  #\$0B
      STAA  \$02
      RTS

TN_CW LDAA  #\$04
      STAA  \$02
      RTS

TN_CCW      LDAA  #\$14
      STAA  \$02
      RTS

```

```

*****
* WINCH SERVO *
*****

```

```

      ORG  \$9200
S_WINCH      LDAB  #50
      CBA
      BGT  WN_CW
      BLT  WN_CCW

      LDAA  #\$0B
      STAA  \$08
      LDAA  #\$A0
      STAA  \$09
      RTS

WN_CW LDAA  #\$04
      STAA  \$08
      LDAA  #\$A0
      STAA  \$09
      RTS

WN_CCW      LDAA  #\$14
      STAA  \$08
      LDAA  #\$A0
      STAA  \$09

```

```

RTS

*****
* LOCK SERVO *
*****

        ORG     $9300
S_LOCK  LDAB    #50
        CBA
        BGT     LK_CW
        BLT     LK_CCW

        LDAA   #$0B
        STAA   $02
        RTS

LK_CW   LDAA   #$04
        STAA   $02
        RTS

LK_CCW  LDAA   #$14
        STAA   $02
        RTS

*****
* INTURRUPT SUBROUTINES *
*****

HANDLE_OC5:
        LDX     #BASE
        BCLR    TFLG1,X      %11110111
        LDAA   0,X
        ANDA   #%00001000
        BEQ    OC5DOWN
        LDD    $08
        BRA    OC5END
OC5DOWN
        LDD    #28960
OC5END
        ADDD   TOC5,X
        STD    TOC5,X
        RTI

HANDLE_OC4:
        LDX     #BASE
        BCLR    TFLG1,X      %11101111
        LDAA   0,X
        ANDA   #%00010000
        BEQ    OC4DOWN
        LDD    $08
        BRA    OC4END
OC4DOWN
        LDD    #28960
OC4END
        ADDD   TOC4,X
        STD    TOC4,X
        RTI

```

```
HANDLE_OC3:
    LDX    #BASE
    BCLR   TFLG1,X    %11011111
    LDAA   0,X
    ANDA   #%00100000
    BEQ    OC3DOWN
    LDD    $08
    BRA    OC3END
```

```
OC3DOWN
    LDD    #28960
```

```
OC3END
    ADDD   TOC3,X
    STD    TOC3,X
    RTI
```

```
HANDLE_OC2:
    LDX    #BASE
    BCLR   TFLG1,X    %10111111
    LDAA   0,X
    ANDA   #%01000000
    BEQ    OC2DOWN
    LDD    $08
    BRA    OC2END
```

```
OC2DOWN
    LDD    #28960
```

```
OC2END
    ADDD   TOC2,X
    STD    TOC2,X
    RTI
```

## Appendix C – Vector Processing Unit Code

```

*****
*                                     *
*                               Mr. T Processor 2                               *
*                                     *
*   Mr. T Processor 2 is called the VPU, which stands for Vector Processing   *
*   Unit.                                                                     *
*   This uses the floating point package provided by Motorola (Written by    *
*   Gordon Doughman). I have defined below which portion of the code is mine, and *
*   which portion is his. Full documentation of his code and what it does can be *
*   found on the Motorola website. My code will do the following:           *
*   *   Interact with the Master Processor using SPI                         *
*   *   Act based on instructions sent from Master                          *
*   *   Initialize and read input from a mouse through the PAK-IV           *
*   *   Analyze this data to compute positioning relative to the start      *
*   *   Compute the release time of the device to strike the target         *
*                                     *
*****

*****
*   HC11FP Constants   *
*****

                ORG    $0000

FPACC1EX        RMB    1          FLOATING POINT ACCUMULATOR #1..
FPACC1MN        RMB    3
MANTSGN1        RMB    1          MANTISSA SIGN FOR FPACC1 (0=+, FF=-).
FPACC2EX        RMB    1          FLOATING POINT ACCUMULATOR #2.
FPACC2MN        RMB    3
MANTSGN2        RMB    1          MANTISSA SIGN FOR FPACC2 (0=+, FF=-).

FLTfMTER        EQU    1          floating point format error in ASCFLT
OVFERR          EQU    2          floating point overflow error
UNFERR          EQU    3          floating point underflow error
DIVOERR         EQU    4          division by 0 error
TOLGSMER        EQU    5          number too large or small to convert to int.
NSQRTERR        EQU    6          tried to take the square root of negative #
TAN90ERR        EQU    7          TANGent of 90 degrees attempted

*****
*   My Constants and Variables   *
*****

                ORG    $2000

DELTA_X_16      RMB    2
DELTA_Y_16      RMB    2
DELTA_X_FP      RMB    4
DELTA_Y_FP      RMB    4
RET0            RMB    1
RET1            RMB    1
RET2            RMB    1
ABSOLUTE_X      RMB    4
ABSOLUTE_Y      RMB    4
ABSOLUTE_THETA  RMB    4
TEMP_X_FP       RMB    4
TEMP_Y_FP       RMB    4
TEMP_THETA      RMB    4
MOUSE_ENABLE    RMB    1
DIVISOR         RMB    4
MAX             RMB    4
MIN            RMB    4

DISTANCE        EQU    $0230
V_GET_X         EQU    $01

```

V_GET_Y	EQU	\$02
V_GET_THETA	EQU	\$03
V_START_MOUSE	EQU	\$04
V_STOP_MOUSE	EQU	\$05
V_RESET_M_CNT	EQU	\$06
V_RESET_ANGLE	EQU	\$07
V_COMP_DIST	EQU	\$08
BASE	EQU	\$1000
STACK	EQU	\$7000
PORTA	EQU	\$00
PIOC	EQU	\$02
PORTC	EQU	\$03
PORTB	EQU	\$04
PORTCL	EQU	\$05
DDRC	EQU	\$07
PORTD	EQU	\$08
DDRD	EQU	\$09
PORTE	EQU	\$0A
CFORC	EQU	\$0B
OC1M	EQU	\$0C
OC1D	EQU	\$0D
TCNT	EQU	\$0E
TIC1	EQU	\$10
TIC2	EQU	\$12
TIC3	EQU	\$14
TOC1	EQU	\$16
TOC2	EQU	\$18
TOC3	EQU	\$1A
TOC4	EQU	\$1C
TI4/O5	EQU	\$1E
TCTL1	EQU	\$20
TCTL2	EQU	\$21
TMSK1	EQU	\$22
TFLG1	EQU	\$23
TMSK2	EQU	\$24
TFLG2	EQU	\$25
PACTL	EQU	\$26
PACNT	EQU	\$27
SPCR	EQU	\$28
SPSR	EQU	\$29
SPDR	EQU	\$2A
BAUD	EQU	\$2B
SCCR1	EQU	\$2C
SCCR2	EQU	\$2D
SCSR	EQU	\$2E
SCDR	EQU	\$2F
ADCTL	EQU	\$30
ADR1	EQU	\$31
ADR2	EQU	\$32
ADR3	EQU	\$33
ADR4	EQU	\$34
BPROT	EQU	\$35
EPROG	EQU	\$36
OPTION	EQU	\$39
COPRST	EQU	\$3A
PPROG	EQU	\$3B
HPRIO	EQU	\$3C
INIT	EQU	\$3D
TEST	EQU	\$3E
CONFIG	EQU	\$3F
BIT0	EQU	%00000001
BIT1	EQU	%00000010
BIT2	EQU	%00000100
BIT3	EQU	%00001000
BIT4	EQU	%00010000
BIT5	EQU	%00100000
BIT6	EQU	%01000000
BIT7	EQU	%10000000
BIT543	EQU	%00111000



```

***
* SCI Int Vector
***
        ORG     $00C7
        JMP     SPI_ISR

*****
*       My Main Function       *
*****

        ORG     $8000

*****
*   INITIALIZATION   *
*****

        LDS     #STACK

        LDX     #DELTA_X_16
        LDAA    #52

***
*   Initialize Memory
***

LOOP1   CLR     0,X
        INX
        DECA
        BNE     LOOP1

***
*   Set The Divisor
***

        LDD     #DISTANCE
        JSR     Convert_D
        JSR     TFR1TO2

        LDD     #$0000
        JSR     Convert_D
        JSR     FLTDIV
        LDX     #DIVISOR
        JSR     PUTFPAC1

***
*   Set Max and Min
***

        LDD     #$0002
        JSR     Convert_D
        LDX     #MAX
        JSR     PUTFPAC1

        LDX     #FPACC1EX
        LDAA    #$FF
        STAA   4,X
        LDX     #MIN
        JSR     PUTFPAC1

***
*   Init Systems
***

        JSR     Init_SCI
        JSR     Init_SPI

***
*   Main Loop
***

        WAI
MAIN_LOOP
        LDAA    MOUSE_ENABLE
        CMPA   #$FF
        BNE     MAIN_LOOP
        JSR     Get_Local
        JSR     Compute_Vectors
        BRA     MAIN_LOOP

*****

```

```

Calc_Dist:
    LDD    #$AA
    RTS

*****

Check_Status:
    LDX    #BASE
    LDAA   #$E9
    JSR    Send_Rcv_3
    LDAA   #$60
    CMPA   RET0
    BNE    C_S_1
    LDAA   #8
    CMPA   RET1
    BNE    C_S_1
    LDAA   #200
    CMPA   RET2
    BNE    C_S_1
    CLRA
    RTS

C_S_1
    LDAA   #$FF
    RTS

*****

Clear_Angle:
    PSHA
    CLRA
    LDX    #TEMP_THETA
    STAA   0,X
    STAA   1,X
    STAA   2,X
    STAA   3,X
    LDS    #ABSOLUTE_THETA
    STAA   0,X
    STAA   1,X
    STAA   2,X
    STAA   3,X
    PULA
    RTS

*****

Clear_Counter:
    PSHA
    CLRA
    LDX    #TEMP_X_FP
    STAA   0,X
    STAA   1,X
    STAA   2,X
    STAA   3,X
    LDX    #TEMP_Y_FP
    STAA   0,X
    STAA   1,X
    STAA   2,X
    STAA   3,X
    LDX    #ABSOLUTE_X
    STAA   0,X
    STAA   1,X
    STAA   2,X
    STAA   3,X
    LDX    #ABSOLUTE_Y
    STAA   0,X
    STAA   1,X
    STAA   2,X
    STAA   3,X
    PULA
    RTS

*****

```

```

Compute_Vectors:
    LDX    #DELTA_X_FP
    JSR    GETFPAC1
    LDX    #DIVISOR
    JSR    FLTMUL
    LDX    #ABSOLUTE_THETA
    JSR    FLTADD
    LDX    #MAX
    JSR    GETFPAC2
    JSR    FLTCMP
    BLE    C_V_1
    JSR    FLTSUB
C_V_1
    LDX    #MIN
    JSR    GETFPAC2
    JSR    FLTCMP
    BLE    C_V_2
    JSR    FLTSUB
C_V_2
    LDX    #TEMP_THETA
    JSR    PUTFPAC1

    LDX    #DELTA_Y_FP
    JSR    GETFPAC2
    JSR    FLTCOS
    JSR    FLTMUL
    LDX    #TEMP_X_FP
    JSR    PUTFPAC1

    LDX    #TEMP_THETA
    JSR    GETFPAC1
    LDX    #DELTA_Y_FP
    JSR    GETFPAC2
    JSR    FLTSIN
    JSR    FLTMUL
    LDX    #TEMP_Y_FP
    JSR    PUTFPAC1

    LDX    #ABSOLUTE_X
    JSR    GETFPAC1
    LDX    #TEMP_X_FP
    JSR    GETFPAC2
    JSR    FLTADD
    JSR    PUTFPAC1

    LDX    #ABSOLUTE_Y
    JSR    GETFPAC1
    LDX    #TEMP_Y_FP
    JSR    GETFPAC2
    JSR    FLTADD
    JSR    PUTFPAC1

    PSHA
    PSHB
    LDX    #TEMP_X_FP
    LDY    #ABSOLUTE_X
    LDD    0,X
    STD    0,Y
    LDD    2,X
    STD    2,Y
    LDX    #TEMP_Y_FP
    LDY    #ABSOLUTE_Y
    LDD    0,X
    STD    0,Y
    LDD    2,X
    STD    2,Y
    LDX    #TEMP_THETA
    LDY    #ABSOLUTE_THETA
    LDD    0,X
    STD    0,Y
    LDD    2,X
    STD    2,Y

```

```

        PULB
        PULA
        RTS

*****

Conv_16_32:
        PSHA
        PSHB
        LDX    #FPACC1EX
        LDD    DELTA_X_16
        STD    2,X
        JSR    SINT2FLT
        LDX    #DELTA_X_FP
        JSR    PUTFPAC1
        LDX    #FPACC1EX
        LDD    DELTA_Y_16
        STD    2,X
        JSR    SINT2FLT
        LDX    #DELTA_X_FP
        JSR    PUTFPAC1
        PULB
        PULA
        RTS

*****

Convert_D:
        LDX    #FPACC1EX
        STD    2,X
        LDD    #00
        STD    0,X
        STAA   4,X
        JSR    UINT2FLT
        RTS

*****

Disable_Mouse:
        PSHA
        LDAA   #00
        STAA   MOUSE_ENABLE
        PULA
        RTS

*****

Get_Local:
        LDAA   #EB
        JSR    Send_Rcv_3
        LDD    #00
        BRCLR  RET0    BIT4    S_L_1
        LDAA   #FF
S_L_1:
        LDAB   RET1
        STD    DELTA_X_16
        LDD    #00
        BRCLR  RET0    BIT5    S_L_2
        LDAA   #FF
S_L_2:
        LDAB   RET2
        STD    DELTA_Y_16
        RTS

*****

Init_Mouse:
        PSHA
        LDAA   #FF
        JSR    Send_PAK
        LDAA   #02
        JSR    Send_PAK
        LDAA   #F0

```

```

        JSR     Send_Mouse
        LDAA   #$E8
        JSR     Send_Mouse
        LDAA   #$03
        JSR     Send_Mouse
        LDAA   #$F3
        JSR     Send_Mouse
        LDAA   #$C8
        JSR     Send_Mouse
        JSR     Check_Status
        CMPA   #$00
        BNE    Init_Mouse
        LDAA   #$FF
        STAA   MOUSE_ENABLE
        PULA
        RTS

*****

Init_SPI:
        LDX     #BASE
        BSET   DDRD,X  BIT2
        BSET   DDRD,X  BIT543
        LDAA   #$C7
        STAA   SPCR,X
        CLI
        RTS

*****

Init_SCI:
        PSHA
        LDX     #BASE
        LDAA   #$30
        STAA   BAUD,X
        LDAA   #$00
        STAA   SCCR1,X
        LDAA   #$00
        STAA   SCCR2,X
        PULA
        RTS

*****

Send_Master_8:
        LDX     #BASE
        STAA   SPDR,X
S_M_8_1
        BRCLR  SPSR,X  BIT7    S_M_8_1
        RTS

*****

Send_Master_32:
        PSHA
        LDAA   0,X
        JSR     Send_Master_8
        LDAA   1,X
        JSR     Send_Master_8
        LDAA   2,X
        JSR     Send_Master_8
        LDAA   3,X
        JSR     Send_Master_8
        PULA
        RTS

*****

Send_Mouse:
        LDX     #BASE
        PSHB
        LDAB   #$0B
        STAB   SCDR,X

```

```

S_M_1      BRCLR   SCSR,X BIT5   S_M_1
           STAA    SCDR,X

S_M_2      BRCLR   SCSR,X BIT5   S_M_2
           PULB
           RTS

*****

Send_PAK:
           LDX     #BASE
           STAA    SCDR,X

S_P_1      BRCLR   SCSR,X BIT6   S_P_1
           RTS

*****

Send_Rcv_3:
           LDX     #BASE
           PSHA
           LDAA    #0B
           STAA    SCDR,X

S_R_3_1    BRCLR   SCSR,X BIT6   S_R_3_1;   BYTE SENT?
           PULA
           STAA    SCDR,X;           SEND BYTE

S_R_3_2    BRCLR   SCSR,X BIT5   S_R_3_2;   BYTE RECEIVED?
           LDAA    SCDR,X
           STAA    RET0

S_R_3_3    BRCLR   SCSR,X BIT5   S_R_3_3;   BYTE RECEIVED?
           LDAA    SCDR,X
           STAA    RET1

S_R_3_4    BRCLR   SCSR,X BIT5   S_R_3_4;   BYTE RECEIVED?
           LDAA    SCDR,X
           STAA    RET2
           RTS

*****

SPI_ISR:
           LDX     #BASE
           BRCLR   SPSR,X BIT7   RT_SPI

           LDAA    SPDR,X
           CMPA    #V_GET_X
           BEQ     GET_X
           CMPA    #V_GET_Y
           BEQ     GET_Y
           CMPA    #V_GET_THETA
           BEQ     GET_THETA
           CMPA    #V_START_MOUSE
           BEQ     START_MOUSE
           CMPA    #V_STOP_MOUSE
           BEQ     STOP_MOUSE
           CMPA    #V_RESET_M_CNT
           BEQ     RESET_M_CNT
           CMPA    #V_RESET_ANGLE
           BEQ     RESET_ANGLE
           CMPA    #V_COMP_DIST
           BEQ     COMP_DIST
           BRA     SPI_ISR_ERROR

GET_X
           LDX     #ABSOLUTE_X
           JSR     Send_Master_8
           JSR     Send_Master_32
           BRA     RT_SPI

```

```

GET_Y
    LDX    #ABSOLUTE_Y
    JSR    Send_Master_8
    JSR    Send_Master_32
    BRA    RT_SPI

GET_THETA
    LDX    #ABSOLUTE_THETA
    JSR    Send_Master_8
    JSR    Send_Master_32
    BRA    RT_SPI

START_MOUSE
    JSR    Init_Mouse
    JSR    Send_Master_8
    BRA    RT_SPI

STOP_MOUSE
    JSR    Disable_Mouse
    JSR    Send_Master_8
    BRA    RT_SPI

RESET_M_CNT
    JSR    Init_Mouse
    JSR    Clear_Counter
    JSR    Send_Master_8
    BRA    RT_SPI

RESET_ANGLE
    JSR    Clear_Angle
    JSR    Send_Master_8
    BRA    RT_SPI

COMP_DIST
    JSR    Send_Master_8
    JSR    Calc_Dist
    JSR    Send_Master_8
    TBA
    JSR    Send_Master_8
    BRA    RT_SPI

SPI_ISR_ERROR
    LDAA   $#FF
    JSR    Send_Master_8

RT_SPI
    RTI

```

```

*****
*           End My Code           *
*****

```

```

*****
*
*           ASCII TO FLOATING POINT ROUTINE           *
*
*   This routine will accept most any ASCII floating point format
*   and return a 32-bit floating point number.  The following are
*   some examples of legal ASCII floating point numbers.
*
*   20.095
*   0.125
*   7.2984E10
*   167.824E5
*   5.9357E-7
*   500
*
*   The floating point number returned is in "FPACC1".
*
*
*   The exponent is biased by 128 to facilitate floating point
*
*****

```

```

*      comparisons.  A pointer to the ASCII string is passed to the      *
*      routine in the D-register.                                         *
*                                                                           *
*      *
*      *
*      *
*****
*
*
*      ORG      $0000
*
*      FPACC1EX RMB  1          FLOATING POINT ACCUMULATOR #1..
*      FPACC1MN RMB  3
*      MANTSGN1 RMB  1          MANTISSA SIGN FOR FPACC1 (0=+, FF=-).
*      FPACC2EX RMB  1          FLOATING POINT ACCUMULATOR #2.
*      FPACC2MN RMB  3
*      MANTSGN2 RMB  1          MANTISSA SIGN FOR FPACC2 (0=+, FF=-).
*
*
*      FLTFMTER EQU  1
*
*      LOCAL VARIABLES (ON STACK POINTED TO BY Y)
*
EXPSIGN EQU  0          EXPONENT SIGN (0=+, FF=-).
PWR10EXP EQU  1          POWER 10 EXPONENT.
*
*
*      ORG      $C000          (TEST FOR EVB)
*
ASCFLT  EQU  *
        PSHX          SAVE POINTER TO ASCII STRING.
        JSR  PSHFPAC2  SAVE FPACC2.
        LDX  #0        PUSH ZEROS ON STACK TO INITIALIZE LOCALS.
        PSHX          ALLOCATE 2 BYTES FOR LOCALS.
        STX  FPACC1EX  CLEAR FPACC1.
        STX  FPACC1EX+2
        CLR  MANTSGN1  MAKE THE MANTISSA SIGN POSITIVE INITIALLY.
        TSY          POINT TO LOCALS.
        LDX  6,Y       GET POINTER TO ASCII STRING.
ASCFLT1 LDAA  0,X       GET 1ST CHARACTER IN STRING.
        JSR  NUMERIC   IS IT A NUMBER.
        BCS  ASCFLT4   YES. GO PROCESS IT.
*
*      LEADING MINUS SIGN ENCOUNTERED?
*
ASCFLT2 CMPA  #'-       NO. IS IT A MINUS SIGN?
        BNE  ASCFLT3   NO. GO CHECK FOR DECIMAL POINT.
        COM  MANTSGN1  YES. SET MANTISSA SIGN. LEADING MINUS BEFORE?
        INX          POINT TO NEXT CHARACTER.
        LDAA  0,X       GET IT.
        JSR  NUMERIC   IS IT A NUMBER?
        BCS  ASCFLT4   YES. GO PROCESS IT.
*
*      LEADING DECIMAL POINT?
*
ASCFLT3 CMPA  #'.'       IS IT A DECIMAL POINT?
        BNE  ASCFLT5   NO. FORMAT ERROR.
        INX          YES. POINT TO NEXT CHARACTER.
        LDAA  0,X       GET IT.
        JSR  NUMERIC   MUST HAVE AT LEAST ONE DIGIT AFTER D.P.
        BCC  ASCFLT5   GO REPORT ERROR.
        JMP  ASCFLT11  GO BUILD FRACTION.
*
*      FLOATING POINT FORMAT ERROR
*
ASCFLT5 INS          DE-ALLOCATE LOCALS.
        INS
        JSR  PULFPAC2  RESTORE FPACC2.
        PULX          GET POINTER TO TERMINATING CHARACTER IN STRING.
        LDAA  #FLTFMTER  FORMAT ERROR.
        SEC          SET ERROR FLAG.
        RTS          RETURN.
*

```



```

*          PRE DECIMAL POINT MANTISSA BUILD
*
ASCFLT4  LDAA   0,X
        JSR    NUMERIC
        BCC   ASCFLT10
        JSR    ADDNXTD
        INX
        BCC   ASCFLT4
*
*          PRE DECIMAL POINT MANTISSA OVERFLOW
*
ASCFLT6  INC    FPACC1EX      INC FOR EACH DIGIT ENCOUNTERED PRIOR TO D.P.
        LDAA   0,X          GET NEXT CHARACTER.
        INX                    POINT TO NEXT.
        JSR    NUMERIC      IS IT S DIGIT?
        BCS   ASCFLT6      YES. KEEP BUILDING POWER 10 MANTISSA.
        CMPA  #'.'         NO. IS IT A DECIMAL POINT?
        BNE   ASCFLT7      NO. GO CHECK FOR THE EXPONENT.
*
*          ANY FRACTIONAL DIGITS ARE NOT SIGNIFIGANT
*
ASCFLT8  LDAA   0,X          GET THE NEXT CHARACTER.
        JSR    NUMERIC      IS IT A DIGIT?
        BCC   ASCFLT7      NO. GO CHECK FOR AN EXPONENT.
        INX                    POINT TO THE NEXT CHARACTER.
        BRA   ASCFLT8      FLUSH REMAINING DIGITS.
ASCFLT7  CMPA  #'E          NO. IS IT THE EXPONENT?
        BEQ   ASCFLT13     YES. GO PROCESS IT.
        JMP   FINISH       NO. GO FINISH THE CONVERSION.
*
*          PROCESS THE EXPONENT
*
ASCFLT13 INX                    POINT TO NEXT CHARACTER.
        LDAA   0,X          GET THE NEXT CHARACTER.
        JSR    NUMERIC      SEE IF IT'S A DIGIT.
        BCS   ASCFLT9      YES. GET THE EXPONENT.
        CMPA  #'-'         NO. IS IT A MINUS SIGN?
        BEQ   ASCFLT15     YES. GO FLAG A NEGATIVE EXPONENT.
        CMPA  #'+'         NO. IS IT A PLUS SIGN?
        BEQ   ASCFLT16     YES. JUST IGNORE IT.
        BRA   ASCFLT5      NO. FORMAT ERROR.
ASCFLT15 COM  EXPSIGN,Y     FLAG A NEGATIVE EXPONENT. IS IT 1ST?
ASCFLT16 INX                    POINT TO NEXT CHARACTER.
        LDAA   0,X          GET NEXT CHARACTER.
        JSR    NUMERIC      IS IT A NUMBER?
        BCC   ASCFLT5      NO. FORMAT ERROR.
ASCFLT9  SUBA  #$30         MAKE IT BINARY.
        STAA  PWR10EXP,Y   BUILD THE POWER 10 EXPONENT.
        INX                    POINT TO NEXT CHARACTER.
        LDAA   0,X          GET IT.
        JSR    NUMERIC      IS IT NUMERIC?
        BCC   ASCFLT14     NO. GO FINISH UP THE CONVERSION.
        LDAB  PWR10EXP,Y   YES. GET PREVIOUS DIGIT.
        LSLB                    MULT. BY 2.
        LSLB                    NOW BY 4.
        ADDB  PWR10EXP,Y   BY 5.
        LSLB                    BY 10.
        SUBA  #$30         MAKE SECOND DIGIT BINARY.
        ABA                    ADD IT TO FIRST DIGIT.
        STAA  PWR10EXP,Y
        CMPA  #38          IS THE EXPONENT OUT OF RANGE?
        BHI   ASCFLT5      YES. REPORT ERROR.
ASCFLT14 LDAA  PWR10EXP,Y   GET POWER 10 EXPONENT.
        TST  EXPSIGN,Y     WAS IT NEGATIVE?
        BPL  ASCFLT12     NO. GO ADD IT TO BUILT 10 PWR EXPONENT.
        NEGA
ASCFLT12 ADDA  FPACC1EX     FINAL TOTAL PWR 10 EXPONENT.
        STAA  FPACC1EX     SAVE RESULT.
        BRA   FINISH       GO FINISH UP CONVERSION.
*
*          PRE-DECIMAL POINT NON-DIGIT FOUND, IS IT A DECIMAL POINT?
*
ASCFLT10 CMPA  #'.'         IS IT A DECIMAL POINT?

```

```

BNE ASCFLT7 NO. GO CHECK FOR THE EXPONENT.
INX YES. POINT TO NEXT CHARACTER.
*
* POST DECIMAL POINT PROCESSING
*
ASCFLT11 LDAA 0,X GET NEXT CHARACTER.
JSR NUMERIC IS IT NUMERIC?
BCC ASCFLT7 NO. GO CHECK FOR EXPONENT.
BSR ADDNXTD YES. ADD IN THE DIGIT.
INX POINT TO THE NEXT CHARACTER.
BCS ASCFLT8 IF OVER FLOW, FLUSH REMAINING DIGITS.
DEC FPACC1EX ADJUST THE 10 POWER EXPONENT.
BRA ASCFLT11 PROCESS ALL FRACTIONAL DIGITS.
*
*
*
ADDNXTD LDAA FPACC1MN GET UPPER 8 BITS.
STAA FPACC2MN COPY INTO FPACC2.
LDD FPACC1MN+1 GET LOWER 16 BITS OF MANTISSA.
STD FPACC2MN+1 COPY INTO FPACC2.
LSLD MULT. BY 2.
ROL FPACC1MN OVERFLOW?
BCS ADDNXTD1 YES. DON'T ADD THE DIGIT IN.
LSLD MULT BY 4.
ROL FPACC1MN OVERFLOW?
BCS ADDNXTD1 YES. DON'T ADD THE DIGIT IN.
ADDD FPACC2MN+1 BY 5.
PSHA SAVE A.
LDAA FPACC1MN GET UPPER 8 BITS.
ADCA #0 ADDIN POSSABLE CARRY FROM LOWER 16 BITS.
ADDA FPACC2MN ADD IN UPPER 8 BITS.
STAA FPACC1MN SAVE IT.
PULA RESTORE A.
BCS ADDNXTD1 OVERFLOW? IF SO DON'T ADD IT IN.
LSLD BY 10.
ROL FPACC1MN
STD FPACC1MN+1 SAVE THE LOWER 16 BITS.
BCS ADDNXTD1 OVERFLOW? IF SO DON'T ADD IT IN.
LDAB 0,X GET CURRENT DIGIT.
SUBB #$30 MAKE IT BINARY.
CLRA 16-BIT.
ADDD FPACC1MN+1 ADD IT IN TO TOTAL.
STD FPACC1MN+1 SAVE THE RESULT.
LDAA FPACC1MN GET UPPER 8 BITS.
ADCA #0 ADD IN POSSIBLE CARRY. OVERFLOW?
BCS ADDNXTD1 YES. COPY OLD MANTISSA FROM FPACC2.
STAA FPACC1MN NO. EVERYTHING OK.
RTS RETURN.
ADDNXTD1 LDD FPACC2MN+1 RESTORE THE ORIGINAL MANTISSA BECAUSE
STD FPACC1MN+1 OF OVERFLOW.
LDAA FPACC2MN
STAA FPACC1MN
RTS RETURN.
*
*
*
* NOW FINISH UP CONVERSION BY MULTIPLYING THE RESULTANT MANTISSA
* BY 10 FOR EACH POSITIVE POWER OF 10 EXPONENT RECIEVED OR BY .1
* (DIVIDE BY 10) FOR EACH NEGATIVE POWER OF 10 EXPONENT RECIEVED.
*
*
FINISH EQU *
STX 6,Y SAVE POINTER TO TERMINATING CHARACTER IN STRING.
LDX #FPACC1EX POINT TO FPACC1.
JSR CHCK0 SEE IF THE NUMBER IS ZERO.
BEQ FINISH3 QUIT IF IT IS.
LDAA FPACC1EX GET THE POWER 10 EXPONENT.
STAA PWR10EXP,Y SAVE IT.
LDAA #$80+24 SET UP INITIAL EXPONENT (# OF BITS + BIAS).
STAA FPACC1EX
JSR FPNORM GO NORMALIZE THE MANTISSA.
TST PWR10EXP,Y IS THE POWER 10 EXPONENT POSITIVE OR ZERO?
BEQ FINISH3 IT'S ZERO, WE'RE DONE.

```

```

BPL      FINISH1      IT'S POSITIVE MULTIPLY BY 10.
LDX      #CONSTP1    NO. GET CONSTANT .1 (DIVIDE BY 10).
JSR      GETFPAC2    GET CONSTANT INTO FPACC2.
NEG      PWR10EXP,Y  MAKE THE POWER 10 EXPONENT POSITIVE.
BRA      FINISH2     GO DO THE MULTIPLIES.
FINISH1  LDX          #CONST10    GET CONSTANT '10' TO MULTIPLY BY.
         JSR          GETFPAC2    GET CONSTANT INTO FPACC2.
FINISH2  JSR          FLTMUL      GO MULTIPLY FPACC1 BY FPACC2, RESULT IN FPACC1.
         DEC          PWR10EXP,Y  DECREMENT THE POWER 10 EXPONENT.
         BNE          FINISH2     GO CHECK TO SEE IF WE'RE DONE.
FINISH3  INS          DE-ALLOCATE LOCALS.
         INS
         JSR          PULFPAC2    RESTORE FPACC2.
         PULX
         RTS
*
*
NUMERIC  EQU          *
         CMPA        #'0          IS IT LESS THAN AN ASCII 0?
         BLO         NUMERIC1    YES. NOT NUMERIC.
         CMPA        #'9          IS IT GREATER THAN AN ASCII 9?
         BHI         NUMERIC1    YES. NOT NUMERIC.
         SEC
         RTS          IT WAS NUMERIC. SET THE CARRY.
         RTS          RETURN.
NUMERIC1 CLC          NON-NUMERIC CHARACTER. CLEAR THE CARRY.
         RTS          RETURN.
*
*
FPNORM   EQU          *
         LDX          #FPACC1EX   POINT TO FPACC1.
         BSR          CHCK0      CHECK TO SEE IF IT'S 0.
         BEQ          FPNORM3    YES. JUST RETURN.
         TST          FPACC1MN   IS THE NUMBER ALREADY NORMALIZED?
         BMI         FPNORM3    YES. JUST RETURN..
FPNORM1  LDD          FPACC1MN+1  GET THE LOWER 16 BITS OF THE MANTISSA.
FPNORM2  DEC          FPACC1EX   DECREMENT THE EXPONENT FOR EACH SHIFT.
         BEQ          FPNORM4    EXPONENT WENT TO 0. UNDERFLOW.
         LSLD        SHIFT THE LOWER 16 BITS.
         ROL         FPACC1MN   ROTATE THE UPPER 8 BITS. NUMBER NORMALIZED?
         BPL         FPNORM2    NO. KEEP SHIFTING TO THE LEFT.
         STD         FPACC1MN+1  PUT THE LOWER 16 BITS BACK INTO FPACC1.
FPNORM3  CLC          SHOW NO ERRORS.
         RTS          YES. RETURN.
FPNORM4  SEC          FLAG ERROR.
         RTS          RETURN.
*
*
CHCK0    EQU          *
         PSHB
         PSHA
         LDD         0,X        GET FPACC EXPONENT & HIGH 8 BITS.
         BNE         CHCK01    NOT ZERO. RETURN.
         LDD         2,X        CHECK LOWER 16 BITS.
CHCK01   PULA        RESTORE D.
         PULB
         RTS          RETURN WITH CC SET.
*
*
CONSTP1  FCB         $7D,$4C,$CC,$CD    0.1 DECIMAL
CONST10  FCB         $84,$20,$00,$00    10.0 DECIMAL
*
*
*****
*
*           FPMULT: FLOATING POINT MULTIPLY
*
*   THIS FLOATING POINT MULTIPLY ROUTINE MULTIPLIES "FPACC1" BY
*   "FPACC2" AND PLACES THE RESULT IN TO FPACC1. FPACC2 REMAINS
*   UNCHANGED.
*
*           WORSE CASE = 2319 CYCLES = 1159 uS @ 2MHz
*
*****
*
*
FLTMUL   EQU          *
         JSR          PSHFPAC2    SAVE FPACC2.

```

	LDX	#FPACC1EX	POINT TO FPACC1
	JSR	CHK0	CHECK TO SEE IF FPACC1 IS ZERO.
	BEQ	FPMULT3	IT IS. ANSWER IS 0.
	LDX	#FPACC2EX	POINT TO FPACC2.
	JSR	CHK0	IS IT 0?
	BNE	FPMULT4	NO. CONTINUE.
	CLRA		CLEAR D.
	CLRB		
	STD	FPACC1EX	MAKE FPACC1 0.
	STD	FPACC1MN+1	
	BRA	FPMULT3	RETURN.
FPMULT4	LDAA	MANTSGN1	GET FPACC1 EXPONENT.
	EORA	MANTSGN2	SET THE SIGN OF THE RESULT.
	STAA	MANTSGN1	SAVE THE SIGN OF THE RESULT.
	LDAA	FPACC1EX	GET FPACC1 EXPONENT.
	ADDA	FPACC2EX	ADD IT TO FPACC2 EXPONENT.
	BPL	FPMULT1	IF RESULT IS MINUS AND
	BCC	FPMULT2	THE CARRY IS SET THEN:
FPMULT5	LDAA	#OVFERR	OVERFLOW ERROR.
	SEC		SET ERROR FLAG.
	BRA	FPMULT6	RETURN.
FPMULT1	BCS	FPMULT2	IF RESULT IS PLUS & THE CARRY IS SET THEN ALL OK.
	LDAA	#UNFERR	ELSE UNDERFLOW ERROR OCCURED.
	SEC		FLAG ERROR.
	BRA	FPMULT6	RETURN.
FPMULT2	ADDA	#S80	ADD 128 BIAS BACK IN THAT WE LOST.
	STAA	FPACC1EX	SAVE THE NEW EXPONENT.
	JSR	UMULT	GO MULTIPLY THE "INTEGER" MANTISSAS.
FPMULT3	TST	FPACC1EX	WAS THERE AN OVERFLOW ERROR FROM ROUNDING?
	BEQ	FPMULT5	YES. RETURN ERROR.
	CLC		SHOW NO ERRORS.
FPMULT6	JSR	PULFPAC2	RESTORE FPACC2.
	RTS		
	*		
	*		
UMULT	EQU	*	
	LDX	#0	
	PSHX		CREATE PARTIAL PRODUCT REGISTER AND COUNTER.
	PSHX		
	TSX		POINT TO THE VARIABLES.
	LDAA	#24	SET COUNT TO THE NUMBER OF BITS.
	STAA	0,X	
UMULT1	LDAA	FPACC2MN+2	GET THE L.S. BYTE OF THE MULTIPLIER.
	LSRA		PUT L.S. BIT IN CARRY.
	BCC	UMULT2	IF CARRY CLEAR, DON'T ADD MULTIPLICAND TO P.P.
	LDD	FPACC1MN+1	GET MULTIPLICAND L.S. 16 BITS.
	ADDD	2,X	ADD TO PARTIAL PRODUCT.
	STD	2,X	SAVE IN P.P.
	LDAA	FPACC1MN	GET UPPER 8 BITS OF MULTIPLICAND.
	ADCA	1,X	ADD IT W/ CARRY TO P.P.
	STAA	1,X	SAVE TO PARTIAL PRODUCT.
UMULT2	ROR	1,X	ROTATE PARTIAL PRODUCT TO THE RIGHT.
	ROR	2,X	
	ROR	3,X	
	ROR	FPACC2MN	SHIFT THE MULTIPLIER TO THE RIGHT 1 BIT.
	ROR	FPACC2MN+1	
	ROR	FPACC2MN+2	
	DEC	0,X	DONE YET?
	BNE	UMULT1	NO. KEEP GOING.
	TST	1,X	DOES PARTIAL PRODUCT NEED TO BE NORMALIZED?
	BMI	UMULT3	NO. GET ANSWER & RETURN.
	LSL	FPACC2MN	GET BIT THAT WAS SHIFTED OUT OF P.P REGISTER.
	ROL	3,X	PUT IT BACK INTO THE PARTIAL PRODUCT.
	ROL	2,X	
	ROL	1,X	
	DEC	FPACC1EX	FIX EXPONENT.
UMULT3	TST	FPACC2MN	DO WE NEED TO ROUND THE PARTIAL PRODUCT?
	BPL	UMULT4	NO. JUST RETURN.
	LDD	2,X	YES. GET THE LEAST SIGNIFIGANT 16 BITS.
	ADDD	#1	ADD 1.
	STD	2,X	SAVE RESULT.
	LDAA	1,X	PROPIGATE THROUGH.
	ADCA	#0	

```

      STAA   1,X
      BCC   UMULT4      IF CARRY CLEAR ALL IS OK.
      ROR   1,X         IF NOT OVERFLOW. ROTATE CARRY INTO P.P.
      ROR   2,X
      ROR   3,X
      INC   FPACC1EX    UP THE EXPONENT.
UMULT4  INS           TAKE COUNTER OFF STACK.
      PULX           GET M.S. 16 BITS OF PARTIAL PRODUCT.
      STX    FPACC1MN   PUT IT IN FPACC1.
      PULA           GET L.S. 8 BITS OF PARTIAL PRODUCT.
      STAA  FPACC1MN+2  PUT IT IN FPACC1.
      RTS          RETURN.
*
*
*
*****
*                                     *
*          FLOATING POINT ADDITION          *
*
* This subroutine performs floating point addition of the two numbers *
* in FPACC1 and FPACC2. The result of the addition is placed in *
* FPACC1 while FPACC2 remains unchanged. This subroutine performs *
* full signed addition so either number may be of the same or opposite *
* sign. *
*          WORSE CASE = 1030 CYCLES = 515 uS @ 2MHz *
*
*****
*
*
FLTADD  EQU      *
      JSR   PSHFPAC2    SAVE FPACC2.
      LDX  #FPACC2EX    POINT TO FPACC2
      JSR  CHCK0        IS IT ZERO?
      BNE  FLTADD1      NO. GO CHECK FOR 0 IN FPACC1.
FLTADD6  CLC          NO ERRORS.
FLTADD10 JSR  PULFPAC2   RESTORE FPACC2.
      RTS          ANSWER IN FPACC1. RETURN.
FLTADD1  LDX  #FPACC1EX  POINT TO FPACC1.
      JSR  CHCK0        IS IT ZERO?
      BNE  FLTADD2      NO. GO ADD THE NUMBER.
FLTADD4  LDD  FPACC2EX    ANSWER IS IN FPACC2. MOVE IT INTO FPACC1.
      STD  FPACC1EX
      LDD  FPACC2MN+1    MOVE LOWER 16 BITS OF MANTISSA.
      STD  FPACC1MN+1
      LDAA MANTSGN2      MOVE FPACC2 MANTISSA SIGN INTO FPACC1.
      STAA MANTSGN1
      BRA  FLTADD6      RETURN.
FLTADD2  LDAA FPACC1EX    GET FPACC1 EXPONENT.
      CMPA FPACC2EX      ARE THE EXPONENTS THE SAME?
      BEQ  FLTADD7      YES. GO ADD THE MANTISSA'S.
      SUBA FPACC2EX      NO. FPACC1EX-FPACC2EX. IS FPACC1 > FPACC2?
      BPL  FLTADD3      YES. GO CHECK RANGE.
      NEGA #23          NO. FPACC1 < FPACC2. MAKE DIFFERENCE POSITIVE.
      CMPA #23          ARE THE NUMBERS WITHIN RANGE?
      BHI  FLTADD4      NO. FPACC2 IS LARGER. GO MOVE IT INTO FPACC1.
      TAB          PUT DIFFERENCE IN B.
      ADDB FPACC1EX      CORRECT FPACC1 EXPONENT.
      STAB FPACC1EX      SAVE THE RESULT.
      LDX  #FPACC1MN    POINT TO FPACC1 MANTISSA.
      BRA  FLTADD5      GO DENORMALIZE FPACC1 FOR THE ADD.
FLTADD3  CMPA #23          FPACC1 > FPACC2. ARE THE NUMBERS WITHIN RANGE?
      BHI  FLTADD6      NO. ANSWER ALREADY IN FPACC1. JUST RETURN.
      LDX  #FPACC2MN    POINT TO THE MANTISSA TO DENORMALIZE.
FLTADD5  LSR  0,X        SHIFT THE FIRST BYTE OF THE MANTISSA.
      ROR  1,X         THE SECOND.
      ROR  2,X         AND THE THIRD.
      DECA          DONE YET?
      BNE  FLTADD5      NO. KEEP SHIFTING.
FLTADD7  LDAA MANTSGN1    GET FPACC1 MANTISSA SIGN.
      CMPA MANTSGN2      ARE THE SIGNS THE SAME?
      BEQ  FLTADD11     YES. JUST GO ADD THE TWO MANTISSAS.
      TST  MANTSGN1     NO. IS FPACC1 THE NEGATIVE NUMBER?
      BPL  FLTADD8      NO. GO DO FPACC1-FPACC2.

```

```

LDX    FPACC2MN    YES. EXCHANGE FPACC1 & FPACC2 BEFORE THE SUB.
PSHX
LDX    FPACC1MN    GET PART OF FPACC1.
STX    FPACC2MN    PUT IT IN FPACC2.
PULX
STX    FPACC1MN    GET SAVED PORTION OF FPACC2
LDX    FPACC2MN+2  GET LOWER 8 BITS & SIGN OF FPACC2.
PSHX    SAVE IT.
LDX    FPACC1MN+2  GET LOWER 8 BITS & SIGN OF FPACC1.
STX    FPACC2MN+2  PUT IT IN FPACC2.
PULX    GET SAVED PART OF FPACC2.
STX    FPACC1MN+2  PUT IT IN FPACC1.
FLTADD8 LDD    FPACC1MN+1  GET LOWER 16 BITS OF FPACC1.
SUBD   FPACC2MN+1  SUBTRACT LOWER 16 BITS OF FPACC2.
STD    FPACC1MN+1  SAVE RESULT.
LDAA   FPACC1MN    GET HIGH 8 BITS OF FPACC1 MANTISSA.
SBCA   FPACC2MN    SUBTRACT HIGH 8 BITS OF FPACC2.
STAA   FPACC1MN    SAVE THE RESULT. IS THE RESULT NEGATIVE?
BCC    FLTADD9     NO. GO NORMALIZE THE RESULT.
LDAA   FPACC1MN    YES. NEGATE THE MANTISSA.
COMA
PSHA
LDD    FPACC1MN+1  GET LOWER 16 BITS.
COMB   FORM THE ONE'S COMPLEMENT.
COMA
ADDD   #1          FORM THE TWO'S COMPLEMENT.
STD    FPACC1MN+1  SAVE THE RESULT.
PULA   GET UPPER 8 BITS BACK.
ADCA   #0          ADD IN POSSIBLE CARRY.
STAA   FPACC1MN    SAVE RESULT.
LDAA   #$FF       SHOW THAT FPACC1 IS NEGATIVE.
STAA   MANTSGN1
FLTADD9 JSR    FPNORM    GO NORMALIZE THE RESULT.
BCC    FLTADD12    EVERYTHING'S OK SO RETURN.
LDAA   #UNFERR    UNDERFLOW OCCURED DURING NORMALIZATION.
SEC
JMP    FLTADD10    RETURN.
FLTADD12 JMP   FLTADD6    CAN'T BRANCH THAT FAR FROM HERE.
*
FLTADD11 LDD   FPACC1MN+1  GET LOWER 16 BITS OF FPACC1.
ADDD   FPACC2MN+1  ADD IT TO THE LOWER 16 BITS OF FPACC2.
STD    FPACC1MN+1  SAVE RESULT IN FPACC1.
LDAA   FPACC1MN    GET UPPER 8 BITS OF FPACC1.
ADCA   FPACC2MN    ADD IT (WITH CARRY) TO UPPER 8 BITS OF FPACC2.
STAA   FPACC1MN    SAVE THE RESULT.
BCC    FLTADD12    NO OVERFLOW SO JUST RETURN.
ROR    FPACC1MN    PUT THE CARRY INTO THE MANTISSA.
ROR    FPACC1MN+1  PROPAGATE THROUGH MANTISSA.
ROR    FPACC1MN+2
INC    FPACC1EX    UP THE MANTISSA BY 1.
BNE    FLTADD12    EVERYTHING'S OK JUST RETURN.
LDAA   #OVFERR    RESULT WAS TOO LARGE. OVERFLOW.
SEC
JMP    FLTADD10    RETURN.
*
*
*
*****
*
*           FLOATING POINT SUBTRACT SUBROUTINE
*
*   This subroutine performs floating point subtraction ( FPACC1-FPACC2)
*   by inverting the sign of FPACC2 and then calling FLTADD since
*   FLTADD performs complete signed addition.  Upon returning from
*   FLTADD the sign of FPACC2 is again inverted to leave it unchanged
*   from its original value.
*
*
*           WORSE CASE = 1062 CYCLES = 531 uS @ 2MHz
*
*****
*
*
FLTSUB  EQU    *

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```

        BSR      FLTSUB1      INVERT SIGN.
        JSR      FLTADD      GO DO FLOATING POINT ADD.
FLTSUB1  LDAA     MANTSGN2    GET FPACC2 MANTISSA SIGN.
        EORA     #$FF       INVERT THE SIGN.
        STAA    MANTSGN2    PUT BACK.
        RTS      RETURN.
*
*
*
*****
*
*           FLOATING POINT DIVIDE
*
*   This subroutine performs signed floating point divide. The
*   operation performed is FPACC1/FPACC2. The divisor (FPACC2) is left
*   unaltered and the answer is placed in FPACC1. There are several
*   error conditions that can be returned by this routine. They are:
*   a) division by zero. b) overflow. c) underflow. As with all
*   other routines, an error is indicated by the carry being set and
*   the error code being in the A-reg.
*
*
*           WORSE CASE = 2911 CYCLES = 1455 uS @ 2MHz
*
*****
*
*
FLTDIV  EQU      *
        LDX     #FPACC2EX   POINT TO FPACC2.
        JSR     CHCK0      IS THE DIVISOR 0?
        BNE     FLTDIV1    NO. GO SEE IF THE DIVIDEND IS ZERO.
        LDAA    #DIV0ERR   YES. RETURN A DIVIDE BY ZERO ERROR.
        SEC     FLAG ERROR.
        RTS     RETURN.
FLTDIV1 LDX     #FPACC1EX   POINT TO FPACC1.
        JSR     CHCK0      IS THE DIVIDEND 0?
        BNE     FLTDIV2    NO. GO PERFORM THE DIVIDE.
        CLC     YES. ANSWER IS ZERO. NO ERRORS.
        RTS     RETURN.
FLTDIV2 JSR     PSHFPAC2    SAVE FPACC2.
        LDAA    MANTSGN2    GET FPACC2 MANTISSA SIGN.
        EORA    MANTSGN1    SET THE SIGN OF THE RESULT.
        STAA    MANTSGN1    SAVE THE RESULT.
        LDX     #0         SET UP WORK SPACE ON THE STACK.
        PSHX
        PSHX
        PSHX
        LDAA    #24        PUT LOOP COUNT ON STACK.
        PSHA
        TSX
        LDD     FPACC1MN    COMPARE FPACC1 & FPACC2 MANTISSAS.
        CPD     FPACC2MN    ARE THE UPPER 16 BITS THE SAME?
        BNE     FLTDIV3    NO.
        LDAA    FPACC1MN+2  YES. COMPARE THE LOWER 8 BITS.
        CMPA   FPACC2MN+2
FLTDIV3 BHS     FLTDIV4     IS FPACC2 MANTISSA > FPACC1 MANTISSA? NO.
        INC     FPACC2EX   ADD 1 TO THE EXPONENT TO KEEP NUMBER THE SAME.
*
        BNE     FLTDIV14   DID OVERFLOW OCCUR?
FLTDIV8 LDAA    #OVFERR     NO. GO SHIFT THE MANTISSA RIGHT 1 BIT.
        SEC     YES. GET ERROR CODE.
        SEC     FLAG ERROR.
FLTDIV6 PULX    REMOVE WORKSPACE FROM STACK.
        PULX
        PULX
        INS
        JSR     PULFPAC2   RESTORE FPACC2.
        RTS     RETURN.
FLTDIV4 LDD     FPACC1MN+1   DO AN INITIAL SUBTRACT IF DIVIDEND MANTISSA IS
        SUBD   FPACC2MN+1   GREATER THAN DIVISOR MANTISSA.
        STD     FPACC1MN+1
        LDAA    FPACC1MN
        SBCA   FPACC2MN
        STAA    FPACC1MN
        DEC     0,X        SUBTRACT 1 FROM THE LOOP COUNT.

```

```

FLTDIV14 LSR    FPACC2MN    SHIFT THE DIVISOR TO THE RIGHT 1 BIT.
          ROR    FPACC2MN+1
          ROR    FPACC2MN+2
          LDAA  FPACC1EX    GET FPACC1 EXPONENT.
          LDAB  FPACC2EX    GET FPACC2 EXPONENT.
          NEGB
          ABA
          BMI    FLTDIV5    IF RESULT MINUS CHECK CARRY FOR POSS. OVERFLOW.
          BCS    FLTDIV7    IF PLUS & CARRY SET ALL IS OK.
          LDAA  #UNFERR    IF NOT, UNDERFLOW ERROR.
          BRA    FLTDIV6    RETURN WITH ERROR.
FLTDIV5  BCS    FLTDIV8    IF MINUS & CARRY SET OVERFLOW ERROR.
FLTDIV7  ADDA  #$81        ADD BACK BIAS+1 (THE '1' COMPENSATES FOR ALGOR.)
          STAA  FPACC1EX    SAVE RESULT.
FLTDIV9  LDD   FPACC1MN    SAVE DIVIDEND IN CASE SUBTRACTION DOESN'T GO.
          STD   4,X
          LDAA  FPACC1MN+2
          STAA  6,X
          LDD   FPACC1MN+1  GET LOWER 16 BITS FOR SUBTRACTION.
          SUBD  FPACC2MN+1
          STD   FPACC1MN+1  SAVE RESULT.
          LDAA  FPACC1MN    GET HIGH 8 BITS.
          SBCA  FPACC2MN
          STAA  FPACC1MN
          BPL   FLTDIV10   SUBTRACTION WENT OK. GO DO SHIFTS.
          LDD   4,X        RESTORE OLD DIVIDEND.
          STD   FPACC1MN
          LDAA  6,X
          STAA  FPACC1MN+2
FLTDIV10 ROL   3,X        ROTATE CARRY INTO QUOTIENT.
          ROL   2,X
          ROL   1,X
          LSL   FPACC1MN+2  SHIFT DIVIDEND TO LEFT FOR NEXT SUBTRACT.
          ROL   FPACC1MN+1
          ROL   FPACC1MN
          DEC   0,X        DONE YET?
          BNE   FLTDIV9    NO. KEEP GOING.
          COM   1,X        RESULT MUST BE COMPLEMENTED.
          COM   2,X
          COM   3,X
          LDD   FPACC1MN+1  DO 1 MORE SUBTRACT FOR ROUNDING.
          SUBD  FPACC2MN+1  ( DON'T NEED TO SAVE THE RESULT. )
          LDAA  FPACC1MN
          SBCA  FPACC2MN    ( NO NEED TO SAVE THE RESULT. )
          LDD   2,X        GET LOW 16 BITS.
          BCC   FLTDIV11   IF IT DIDNT GO RESULT OK AS IS.
          CLC
          BRA   FLTDIV13   GO SAVE THE NUMBER.
FLTDIV11 ADDD  #1        ROUND UP BY 1.
FLTDIV13 STD   FPACC1MN+1  PUT IT IN FPACC1.
          LDAA  1,X        GET HIGH 8 BITS.
          ADCA  #0
          STAA  FPACC1MN    SAVE RESULT.
          BCC   FLTDIV12   IF CARRY CLEAR ANSWER OK.
          ROR   FPACC1MN    IF NOT OVERFLOW. ROTATE CARRY IN.
          ROR   FPACC1MN+1
          ROR   FPACC1MN+2
FLTDIV12 CLC
          JMP   FLTDIV6    RETURN.

```

```

*
*
*

```

```

*****

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```

*
*           FLOATING POINT TO ASCII CONVERSION SUBROUTINE           *
*
* This subroutine performs floating point to ASCII conversion of    *
* the number in FPACC1. The ascii string is placed in a buffer     *
* pointed to by the X index register. The buffer must be at least  *
* 14 bytes long to contain the ASCII conversion. The resulting     *
* ASCII string is terminated by a zero (0) byte. Upon exit the     *
* X Index register will be pointing to the first character of the  *
* string. FPACC1 and FPACC2 will remain unchanged.                 *
*

```



```

*
*****
*
*
FLTASC EQU *
PSHX SAVE THE POINTER TO THE STRING BUFFER.
LDX #FPACC1EX POINT TO FPACC1.
JSR CHK0 IS FPACC1 0?
BNE FLTASC1 NO. GO CONVERT THE NUMBER.
PULX RESTORE POINTER.
LDD #3000 GET ASCII CHARACTER + TERMINATING BYTE.
STD 0,X PUT IT IN THE BUFFER.
RTS RETURN.

FLTASC1 LDX FPACC1EX SAVE FPACC1.
PSHX
LDX FPACC1MN+1
PSHX
LDAA MANTSGN1
PSHA
JSR PSHFPAC2 SAVE FPACC2.
LDX #0
PSHX ALLOCATE LOCALS.
PSHX
PSHX SAVE SPACE FOR STRING BUFFER POINTER.
TSY POINT TO LOCALS.
LDX 15,Y GET POINTER FROM STACK.
LDAA #20 PUT A SPACE IN THE BUFFER IF NUMBER NOT NEGATIVE.
TST MANTSGN1 IS IT NEGATIVE?
BEQ FLTASC2 NO. GO PUT SPACE.
CLR MANTSGN1 MAKE NUMBER POSITIVE FOR REST OF CONVERSION.
LDAA #'- YES. PUT MINUS SIGN IN BUFFER.

FLTASC2 STAA 0,X
INX POINT TO NEXT LOCATION.
STX 0,Y SAVE POINTER.

FLTASC5 LDX #N99999999 POINT TO CONSTANT 99999999.
JSR GETFPAC2 GET INTO FPACC2.
JSR FLTCMP COMPARE THE NUMBERS. IS FPACC1 > 99999999?
BHI FLTASC3 YES. GO DIVIDE FPACC1 BY 10.
LDX #P99999999 POINT TO CONSTANT 9999999.9
JSR GETFPAC2 MOVE IT INTO FPACC2.
JSR FLTCMP COMPARE NUMBERS. IS FPACC1 > 9999999.9?
BHI FLTASC4 YES. GO CONTINUE THE CONVERSION.
DEC 2,Y DECREMENT THE MULT./DIV. COUNT.
LDX #CONST10 NO. MULTIPLY BY 10. POINT TO CONSTANT.

FLTASC6 JSR GETFPAC2 MOVE IT INTO FPACC2.
JSR FLTMUL
BRA FLTASC5 GO DO COMPARE AGAIN.

FLTASC3 INC 2,Y INCREMENT THE MULT./DIV. COUNT.
LDX #CONSTP1 POINT TO CONSTANT ".1".
BRA FLTASC6 GO DIVIDE FPACC1 BY 10.

FLTASC4 LDX #CONSTP5 POINT TO CONSTANT OF ".5".
JSR GETFPAC2 MOVE IT INTO FPACC2.
JSR FLTADD ADD .5 TO NUMBER IN FPACC1 TO ROUND IT.
LDAB FPACC1EX GET FPACC1 EXPONENT.
SUBB #81 TAKE OUT BIAS +1.
NEGB MAKE IT NEGATIVE.
ADDB #23 ADD IN THE NUMBER OF MANTISSA BITS -1.
BRA FLTASC17 GO CHECK TO SEE IF WE NEED TO SHIFT AT ALL.

FLTASC7 LSR FPACC1MN SHIFT MANTISSA TO THE RIGHT BY THE RESULT (MAKE
ROR FPACC1MN+1 THE NUMBER AN INTEGER).
ROR FPACC1MN+2
DECB DONE SHIFTING?

FLTASC17 BNE FLTASC7 NO. KEEP GOING.
LDAA #1 GET INITIAL VALUE OF "DIGITS AFTER D.P." COUNT.
STAA 3,Y INITIALIZE IT.
LDAA 2,Y GET DECIMAL EXPONENT.
ADDA #8 ADD THE NUMBER OF DECIMAL +1 TO THE EXPONENT.

*
BMI FLTASC8 WAS THE ORIGINAL NUMBER > 99999999?
CMPA #8 YES. MUST BE REPRESENTED IN SCIENTIFIC NOTATION.
BHS FLTASC8 WAS THE ORIGINAL NUMBER < 1?
DECA YES. MUST BE REPRESENTED IN SCIENTIFIC NOTATION.
STAA 3,Y NO. NUMBER CAN BE REPRESENTED IN 7 DIGITS.
MAKE THE DECIMAL EXPONENT THE DIGIT COUNT BEFORE

```

*			THE DECIMAL POINT.
	LDAA	#2	SETUP TO ZERO THE DECIMAL EXPONENT.
FLTASC8	SUBA	#2	SUBTRACT 2 FROM THE DECIMAL EXPONENT.
	STAA	2,Y	SAVE THE DECIMAL EXPONENT.
	TST	3,Y	DOES THE NUMBER HAVE AN INTEGER PART? (EXP. >0)
	BGT	FLTASC9	YES. GO PUT IT OUT.9
	LDAA	#'	NO. GET DECIMAL POINT.
	LDX	0,Y	GET POINTER TO BUFFER.
	STAA	0,X	PUT THE DECIMAL POINT IN THE BUFFER.
	INX		POINT TO NEXT BUFFER LOCATION.
	TST	3,Y	IS THE DIGIT COUNT TILL EXPONENT =0?
	BEQ	FLTASC18	NO. NUMBER IS <.1
	LDAA	#'0	YES. FORMAT NUMBER AS .0XXXXXXX
	STAA	0,X	PUT THE 0 IN THE BUFFER.
	INX		POINT TO THE NEXT LOCATION.
FLTASC18	STX	0,Y	SAVE NEW POINTER VALUE.
FLTASC9	LDX	#DECDIG	POINT TO THE TABLE OF DECIMAL DIGITS.
	LDAA	#7	INITIALIZE THE THE NUMBER OF DIGITS COUNT.
	STAA	5,Y	
FLTASC10	CLR	4,Y	CLEAR THE DECIMAL DIGIT ACCUMULATOR.
FLTASC11	LDD	FPACC1MN+1	GET LOWER 16 BITS OF MANTISSA.
	SUBD	1,X	SUBTRACT LOWER 16 BITS OF CONSTANT.
	STD	FPACC1MN+1	SAVE RESULT.
	LDAA	FPACC1MN	GET UPPER 8 BITS.
	SBCA	0,X	SUBTRACT UPPER 8 BITS.
	STAA	FPACC1MN	SAVE RESULT. UNDERFLOW?
	BCS	FLTASC12	YES. GO ADD DECIMAL NUMBER BACK IN.
	INC	4,Y	ADD 1 TO DECIMAL NUMBER.
	BRA	FLTASC11	TRY ANOTHER SUBTRACTION.
FLTASC12	LDD	FPACC1MN+1	GET FPACC1 MANTISSA LOW 16 BITS.
	ADD	1,X	ADD LOW 16 BITS BACK IN.
	STD	FPACC1MN+1	SAVE THE RESULT.
	LDAA	FPACC1MN	GET HIGH 8 BITS.
	ADCA	0,X	ADD IN HIGH 8 BITS OF CONSTANT.
	STAA	FPACC1MN	SAVE RESULT.
	LDAA	4,Y	GET DIGIT.
	ADDA	#\$30	MAKE IT ASCII.
	PSHX		SAVE POINTER TO CONSTANTS.
	LDX	0,Y	GET POINTER TO BUFFER.
	STAA	0,X	PUT DIGIT IN BUFFER.
	INX		POINT TO NEXT BUFFER LOCATION.
	DEC	3,Y	SHOULD WE PUT A DECIMAL POINT IN THE BUFFER YET?
	BNE	FLTASC16	NO. CONTINUE THE CONVERSION.
	LDAA	#'	YES. GET DECIMAL POINT.
	STAA	0,X	PUT IT IN THE BUFFER.
	INX		POINT TO THE NEXT BUFFER LOCATION.
FLTASC16	STX	0,Y	SAVE UPDATED POINTER.
	PULX		RESTORE POINTER TO CONSTANTS.
	INX		POINT TO NEXT CONSTANT.
	INX		
	INX		
	DEC	5,Y	DONE YET?
	BNE	FLTASC10	NO. CONTINUE CONVERSION OF "MANTISSA".
	LDX	0,Y	YES. POINT TO BUFFER STRING BUFFER.
FLTASC13	DEX		POINT TO LAST CHARACTER PUT IN THE BUFFER.
	LDAA	0,X	GET IT.
	CMPA	#\$30	WAS IT AN ASCII 0?
	BEQ	FLTASC13	YES. REMOVE TRAILING ZEROS.
	INX		POINT TO NEXT AVAILABLE LOCATION IN BUFFER.
	LDAB	2,Y	DO WE NEED TO PUT OUT AN EXPONENT?
	BEQ	FLTASC15	NO. WE'RE DONE.
	LDAA	#'E	YES. PUT AN 'E' IN THE BUFFER.
	STAA	0,X	
	INX		POINT TO NEXT BUFFER LOCATION.
	LDAA	#'+	ASSUME EXPONENT IS POSITIVE.
	STAA	0,X	PUT PLUS SIGN IN THE BUFFER.
	TSTB		IS IT REALLY MINUS?
	BPL	FLTASC14	NO. IS'S OK AS IS.
	NEGB		YES. MAKE IT POSITIVE.
	LDAA	#'-	PUT THE MINUS SIGN IN THE BUFFER.
	STAA	0,X	
FLTASC14	INX		POINT TO NEXT BUFFER LOCATION.
	STX	0,Y	SAVE POINTER TO STRING BUFFER.

```

CLRA          SET UP FOR DIVIDE.
LDX          #10          DIVIDE DECIMAL EXPONENT BY 10.
IDIV
PSHB        SAVE REMAINDER.
XGDX        PUT QUOTIENT IN D.
ADDB        #\$30        MAKE IT ASCII.
LDX          0,Y          GET POINTER.
STAB        0,X          PUT NUMBER IN BUFFER.
INX
PULB        GET SECOND DIGIT.
ADDB        #\$30        MAKE IT ASCII.
STAB        0,X          PUT IT IN THE BUFFER.
INX
FLTASC15    CLR          0,X          TERMINATE STRING WITH A ZERO BYTE.
PULX        CLEAR LOCALS FROM STACK.
PULX
PULX
JSR          PULFPAC2     RESTORE FPACC2.
PULA
STAA        MANTSGN1
PULX        RESTORE FPACC1.
STX          FPACC1MN+1
PULX
STX          FPACC1EX
PULX        POINT TO THE START OF THE ASCII STRING.
RTS        RETURN.

*
*
DECDIG      EQU          *
FCB          \$0F,\$42,\$40  DECIMAL 1,000,000
FCB          \$01,\$86,\$A0  DECIMAL 100,000
FCB          \$00,\$27,\$10  DECIMAL 10,000
FCB          \$00,\$03,\$E8  DECIMAL 1,000
FCB          \$00,\$00,\$64  DECIMAL 100
FCB          \$00,\$00,\$0A  DECIMAL 10
FCB          \$00,\$00,\$01  DECIMAL 1

*
*
P99999999  EQU          *          CONSTANT 999999.9
FCB          \$94,\$74,\$23,\$FE

*
N99999999  EQU          *          CONSTANT 9999999.
FCB          \$98,\$18,\$96,\$7F

*
CONSTP5    EQU          *          CONSTANT .5
FCB          \$80,\$00,\$00,\$00

*
*
FLTCMP      EQU          *
TST          MANTSGN1     IS FPACC1 NEGATIVE?
BPL          FLTCMP2     NO. CONTINUE WITH COMPARE.
TST          MANTSGN2     IS FPACC2 NEGATIVE?
BPL          FLTCMP2     NO. CONTINUE WITH COMPARE.
LDD          FPACC2EX     YES. BOTH ARE NEGATIVE SO COMPARE MUST BE DONE
CPD          FPACC1EX     BACKWARDS. ARE THEY EQUAL SO FAR?
BNE          FLTCMP1     NO. RETURN WITH CONDITION CODES SET.
LDD          FPACC2MN+1   YES. COMPARE LOWER 16 BITS OF MANTISSAS.
CPD          FPACC1MN+1

FLTCMP1    RTS          RETURN WITH CONDITION CODES SET.
FLTCMP2    LDAA         MANTSGN1     GET FPACC1 MANTISSA SIGN.
CMPA        MANTSGN2     BOTH POSITIVE?
BNE          FLTCMP1     NO. RETURN WITH CONDITION CODES SET.
LDD          FPACC1EX     GET FPACC1 EXPONENT & UPPER 8 BITS OF MANTISSA.
CPD          FPACC2EX     SAME AS FPACC2?
BNE          FLTCMP1     NO. RETURN WITH CONDITION CODES SET.
LDD          FPACC1MN+1   GET FPACC1 LOWER 16 BITS OF MANTISSA.
CPD          FPACC2MN+1   COMPARE WITH FPACC2 LOWER 16 BITS OF MANTISSA.
RTS        RETURN WITH CONDITION CODES SET.

*
*
*****
*

```

```

*
*           UNSIGNED INTEGER TO FLOATING POINT
*
*   This subroutine performs "unsigned" integer to floating point
*   conversion of a 16 bit word.  The 16 bit integer must be in the
*   lower 16 bits of FPACC1 mantissa.  The resulting floating point
*   number is returned in FPACC1.
*
*****
*
*
*   UIN2FLT EQU      *
*           LDX      #FPACC1EX    POINT TO FPACC1.
*           JSR      CHCK0        IS IT ALREADY 0?
*           BNE      UIN2FLT1     NO. GO CONVERT.
*           RTS
*   UIN2FLT1 LDAA    #$98          GET BIAS + NUMBER OF BITS IN MANTISSA.
*           STAA    FPACC1EX     INITIALIZE THE EXPONENT.
*           JSR      FPNORM       GO MAKE IT A NORMALIZED FLOATING POINT VALUE.
*           CLC
*           RTS                  RETURN.
*
*
*
*****
*
*           SIGNED INTEGER TO FLOATING POINT
*
*   This routine works just like the unsigned integer to floating
*   point routine except the the 16 bit integer in the FPACC1
*   mantissa is considered to be in two's complement format.  This
*   will return a floating point number in the range -32768 to +32767.
*
*****
*
*
*   SIN2FLT EQU      *
*           LDD      FPACC1MN+1   GET THE LOWER 16 BITS OF FPACC1 MANTISSA.
*           PSHA
*           BPL      SIN2FLT1     IF POSITIVE JUST GO CONVERT.
*           COMA
*           COMB
*           ADDD    #1            TWO'S COMPLEMENT.
*           STD      FPACC1MN+1   PUT IT BACK IN FPACC1 MANTISSA.
*   SIN2FLT1 BSR      UIN2FLT     GO CONVERT.
*           PULA
*           LDAB    #$FF         GET "MINUS SIGN".
*           TSTA
*           BPL      SIN2FLT2     NO. RETURN.
*           STAB    MANTSGN1     YES. SET FPACC1 SIGN BYTE.
*   SIN2FLT2 CLC
*           RTS                  RETURN.
*
*
*
*****
*
*           FLOATING POINT TO INTEGER CONVERSION
*
*   This subroutine will perform "unsigned" floating point to integer
*   conversion.  The floating point number if positive, will be
*   converted to an unsigned 16 bit integer ( 0 <= X <= 65535 ).  If
*   the number is negative it will be converted to a twos complement
*   16 bit integer.  This type of conversion will allow 16 bit
*   addresses to be represented as positive numbers when in floating
*   point format.  Any fractional number part is disregarded
*
*****
*
*
*   FLT2INT EQU      *
*           LDX      #FPACC1EX    POINT TO FPACC1.
*           JSR      CHCK0        IS IT 0?
*           BEQ      FLT2INT3     YES. JUST RETURN.

```

```

LDAB    FPACC1EX    GET FPACC1 EXPONENT.
CMPB    #$81        IS THERE AN INTEGER PART?
BLO     FLT2INT2    NO. GO PUT A 0 IN FPACC1.
TST     MANTSGN1    IS THE NUMBER NEGATIVE?
BMI     FLT2INT1    YES. GO CONVERT NEGATIVE NUMBER.
CMPB    #$90        IS THE NUMBER TOO LARGE TO BE MADE AN INTEGER?
BHI     FLT2INT4    YES. RETURN WITH AN ERROR.
SUBB    #$98        SUBTRACT THE BIAS PLUS THE NUMBER OF BITS.
FLT2INT5 LSR    FPACC1MN    MAKE THE NUMBER AN INTEGER.
ROR     FPACC1MN+1
ROR     FPACC1MN+2
INCB
BNE     FLT2INT5    DONE SHIFTING?
CLR     FPACC1EX    NO. KEEP GOING.
RTS
RTS
RTS    ZERO THE EXPONENT (ALSO CLEARS THE CARRY).

FLT2INT1 CMPB    #$8F        IS THE NUMBER TOO SMALL TO BE MADE AN INTEGER?
BHI     FLT2INT4    YES. RETURN ERROR.
SUBB    #$98        SUBTRACT BIAS PLUS NUMBER OF BITS.
BSR     FLT2INT5    GO DO SHIFT.
LDD     FPACC1MN+1    GET RESULTING INTEGER.
COMA
COMB    MAKE IT NEGATIVE.
ADDD    #1          TWO'S COMPLEMENT.
STD     FPACC1MN+1    SAVE RESULT.
CLR     MANTSGN1    CLEAR MANTISSA SIGN. (ALSO CLEARS THE CARRY)
RTS    RETURN.

FLT2INT4 LDAA    #TOLGSMER    NUMBER TOO LARGE OR TOO SMALL TO CONVERT TO INT.
SEC
RTS    FLAG ERROR.
RTS    RETURN.

FLT2INT2 LDD     #0
STD     FPACC1EX    ZERO FPACC1.
STD     FPACC1MN+1    (ALSO CLEARS THE CARRY)

FLT2INT3 RTS    RETURN.
*
*
*
*****
*
*           SQUARE ROOT SUBROUTINE
*
*   This routine is used to calculate the square root of the floating
*   point number in FPACC1.  If the number in FPACC1 is negative an
*   error is returned.
*
*           WORSE CASE = 16354 CYCLES = 8177 uS @ 2MHz
*
*****
*
*
FLTSQR  EQU     *
LDX     #FPACC1EX    POINT TO FPACC1.
JSR     CHCK0        IS IT ZERO?
BNE     FLTSQR1      NO. CHECK FOR NEGATIVE.
RTS     YES. RETURN.

FLTSQR1 TST     MANTSGN1    IS THE NUMBER NEGATIVE?
BPL     FLTSQR2      NO. GO TAKE ITS SQUARE ROOT.
LDAA    #NSQRTERR    YES. ERROR.
SEC
RTS     FLAG ERROR.
RTS     RETURN.

FLTSQR2 JSR     PSHFPAC2    SAVE FPACC2.
LDAA    #4           GET ITERATION LOOP COUNT.
PSHA
LDX     FPACC1MN+1    SAVE INITIAL NUMBER.
PSHX
LDX     FPACC1EX
PSHX
TSY
BSR     TFR1TO2      POINT TO IT.
LDAA    FPACC2EX     TRANSFER FPACC1 TO FPACC2.
SUBA    #$80        GET FPACC1 EXPONENT.
INCA    COMPENSATE FOR ODD EXPONENTS (GIVES CLOSER GUESS)
BPL     FLTSQR3      REMOVE BIAS FROM EXPONENT.
LSRA    IF NUMBER >1 DIVIDE EXPONENT BY 2 & ADD BIAS.
        IF <1 JUST DIVIDE IT BY 2.

```

```

FLTSQR3  BRA    FLTSQR4    GO CALCULATE THE SQUARE ROOT.
          LSRA           DIVIDE EXPONENT BY 2.
          ADDA          #80    ADD BIAS BACK IN.
FLTSQR4  STAA    FPACC2EX   SAVE EXPONENT/2.
FLTSQR5  JSR    FLTDIV     DIVIDE THE ORIGINAL NUMBER BY THE GUESS.
          JSR    FLTADD     ADD THE "GUESS" TO THE QUOTIENT.
          DEC    FPACC1EX   DIVIDE THE RESULT BY 2 TO PRODUCE A NEW GUESS.
          BSR    TFR1TO2    PUT THE NEW GUESS INTO FPACC2.
          LDD    0,Y        GET THE ORIGINAL NUMBER.
          STD    FPACC1EX   PUT IT BACK IN FPACC1.
          LDD    2,Y        GET MANTISSA LOWER 16 BITS.
          STD    FPACC1MN+1
          DEC    4,Y        BEEN THROUGH THE LOOP 4 TIMES?
          BNE    FLTSQR5    NO. KEEP GOING.
          LDD    FPACC2EX   THE FINAL GUESS IS THE ANSWER.
          STD    FPACC1EX   PUT IT IN FPACC1.
          LDD    FPACC2MN+1
          STD    FPACC1MN+1
          PULX           GET RID OF ORIGINAL NUMBER.
          PULX
          INS           GET RID OF LOOP COUNT VARIABLE.
          JSR    PULFPAC2   RESTORE FPACC2.
          CLC           NO ERRORS.
          RTS

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TFR1TO2  EQU    *
          LDD    FPACC1EX   GET FPACC1 EXPONENT & HIGH 8 BIT OF MANTISSA.
          STD    FPACC2EX   PUT IT IN FPACC2.
          LDD    FPACC1MN+1  GET FPACC1 LOW 16 BITS OF MANTISSA.
          STD    FPACC2MN+1  PUT IT IN FPACC2.
          LDAA   MANTSGN1    TRANSFER THE SIGN.
          STAA   MANTSGN2
          RTS           RETURN.

```

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\*  
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```

*****
*
*           FLOATING POINT SINE
*
*****

```

\*  
\*

```

FLTSIN   EQU    *
          JSR    PSHFPAC2   SAVE FPACC2 ON THE STACK.
          JSR    ANGRED     GO REDUCE THE ANGLE TO BETWEEN +/-PI.
          PSHB           SAVE THE QUAD COUNT.
          PSHA           SAVE THE SINE/COSINE FLAG.
          JSR    DEG2RAD    CONVERT DEGREES TO RADIANS.
          PULA           RESTORE THE SINE/COSINE FLAG.
FLTSIN1  JSR    SINCOS     GO GET THE SINE OF THE ANGLE.
          PULA           RESTORE THE QUAD COUNT.
          CMPA   #2        WAS THE ANGLE IN QUADS 1 OR 2?
          BLS    FLTSIN2   YES. SIGN OF THE ANSWER IS OK.
          COM    MANTSGN1   NO. SINE IN QUADS 3 & 4 IS NEGATIVE.
FLTSIN2  CLC           SHOW NO ERRORS.
          JSR    PULFPAC2   RESTORE FPACC2
          RTS           RETURN.

```

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\*  
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*****
*
*           FLOATING POINT COSINE
*
*****

```

\*  
\*

```

FLTCOS   EQU    *
          JSR    PSHFPAC2   SAVE FPACC2 ON THE STACK.
          JSR    ANGRED     GO REDUCE THE ANGLE TO BETWEEN +/-PI.
          PSHB           SAVE THE QUAD COUNT.

```

```

PSHA                                SAVE THE SINE/COSINE FLAG.
JSR  DEG2RAD                        CONVERT TO RADIANS.
PULA                                RESTORE THE SINE/COSINE FLAG.
EORA  #$01                          COMPLIMENT 90'S COPMLIMENT FLAG FOR COSINE.
JSR  SINCOS                          GO GET THE COSINE OF THE ANGLE.
PULA                                RESTORE THE QUAD COUNT.
CMPA  #1                             WAS THE ORIGINAL ANGLE IN QUAD 1?
BEQ  FLTCOS1                         YES. SIGN IS OK.
CMPA  #4                             WAS IT IN QUAD 4?
BEQ  FLTCOS1                         YES. SIGN IS OK.
COM  MANTSGN1                       NO. COSINE IS NEGATIVE IN QUADS 2 & 3.
FLTCOS1 JMP  FLTSMIN2                FLAG NO ERRORS, RESTORE FPACC2, & RETURN.
*
*
*
*****
*
*                                FLOATING POINT SINE AND COSINE SUBROUTINE
*
*****
*
SINCOS EQU  *
PSHA                                SAVE SINE/COSINE FLAG ON STACK.
LDX  FPACC1MN+1                    SAVE THE VALUE OF THE ANGLE.
PSHX
LDX  FPACC1EX
PSHX
LDAA MANTSGN1
PSHA
LDX  #SINFACCT                     POINT TO THE FACTORIAL TABLE.
PSHX                                SAVE POINTER TO THE SINE FACTORIAL TABLE.
PSHX                                JUST ALLOCATE ANOTHER LOCAL (VALUE NOT IMPORTANT)
LDAA  #$4                           GET INITIAL LOOP COUNT.
PSHA                                SAVE AS LOCAL ON STACK
TSY                                POINT TO LOCALS.
JSR  TFR1TO2                        TRANSFER FPACC1 TO FPACC2.
JSR  FLTMLUL                         GET X^2 IN FPACC1.
TST  10,Y                           ARE WE DOING THE SINE?
BEQ  SINCOS7                        YES. GO DO IT.
LDX  #COSFACT                       NO. GET POINTER TO COSINE FACTORIAL TABLE.
STX  1,Y                             SAVE IT.
JSR  TFR1TO2                        COPY X^2 INTO FPACC2.
BRA  SINCOS4                        GENERATE EVEN POWERS OF "X" FOR COSINE.
SINCOS7 JSR  EXG1AND2                PUT X^2 IN FPACC2 & X IN FPACC1.
SINCOS1 JSR  FLTMLUL                 CREATE X^3,5,7,9 OR X^2,4,6,8.
SINCOS4 LDX  FPACC1MN+1             SAVE EACH ONE ON THE STACK.
PSHX
LDX  FPACC1EX
PSHX
LDAA MANTSGN1
PSHA                                SAVE THE MANTISSA SIGN.
DEC  0,Y                             HAVE WE GENERATED ALL THE POWERS YET?
BNE  SINCOS1                        NO. GO DO SOME MORE.
LDAA  #$4                           SET UP LOOP COUNT.
STAA  0,Y
TSX                                POINT TO POWERS ON THE STACK.
SINCOS2 STX  3,Y                     SAVE THE POINTER.
LDX  1,Y                             GET THE POINTER TO THE FACTORIAL CONSTANTS.
JSR  GETFPACC2                       PUT THE NUMBER IN FPACC2.
INX
INX
INX
INX
STX  1,Y                             SAVE THE POINTER.
LDX  3,Y                             GET POINTER TO POWERS.
LDAA  0,X                             GET NUMBER SIGN.
STAA MANTSGN1                       PUT IN FPACC1 MANTISSA SIGN.
LDD  1,X                             GET LOWER 16-BITS OF THE MANTISSA.
STD  FPACC1EX                       PUT IN FPACC1 MANTISSA.
LDD  3,X                             GET HIGH 8 BITS OF THE MANTISSA & EXPONENT.
STD  FPACC1MN+1                     PUT IT IN FPACC1 EXPONENT & MANTISSA.
JSR  FLTMLUL                         MULTIPLY THE TWO.

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LDX      3,Y      GET POINTER TO POWERS BACK.
LDD      FPACC1MN+1  SAVE RESULT WHERE THE POWER OF X WAS.
STD      3,X
LDD      FPACC1EX
STD      1,X
LDAA     MANTSGN1    SAVE SIGN.
STAA     0,X
INX
INX
INX
INX
INX
DEC      0,Y      DONE?
BNE      SINCO52    NO. GO DO ANOTHER MULTIPLICATION.
LDAA     #$3
STAA     0,Y      GET LOOP COUNT.
SINCO53 LDX      3,Y      POINT TO RESULTS ON THE STACK.
DEX
DEX
DEX
DEX
STX      3,Y      SAVE THE NEW POINTER.
LDAA     0,X      GET NUMBERS SIGN.
STAA     MANTSGN2    PUT IT IN FPACC2.
LDD      1,X      GET LOW 16 BITS OF THE MANTISSA.
STD      FPACC2EX    PUT IN FPACC2.
LDD      3,X      GET HIGH 8 BIT & EXPONENT.
STD      FPACC2MN+1  PUT IN FPACC2.
JSR      FLTADD     GO ADD THE TWO NUMBERS.
DEC      0,Y      DONE?
BNE      SINCO53    NO. GO ADD THE NEXT TERM IN.
TST      10,Y     ARE WE DOING THE SINE?
BEQ      SINCO55    YES. GO PUT THE ORIGINAL ANGLE INTO FPACC2.
LDX      #ONE      NO. FOR COSINE PUT THE CONSTANT 1 INTO FPACC2.
JSR      GETFPAC2
BRA      SINCO56    GO ADD IT TO THE SUM OF THE TERMS.
SINCO55 LDAA     5,Y      GET THE VALUE OF THE ORIGINAL ANGLE.
STAA     MANTSGN2    PUT IT IN FPACC2.
LDD      6,Y
STD      FPACC2EX
LDD      8,Y
STD      FPACC2MN+1
SINCO56 JSR      FLTADD     GO ADD IT TO THE SUM OF THE TERMS.
TSX
XGDX
ADDD     #31
XGDX
TXS
RTS
*
*
ANGRED  EQU      *
CLRA
PSHA
INCA
PSHA
TSY
LDX      #THREE60   POINT TO THE CONSTANT 360.
JSR      GETFPAC2   GET IT INTO FPACC.
TST      MANTSGN1   IS THE INPUT ANGLE NEGATIVE:
BPL      ANGRED1    NO. SKIP THE ADD.
JSR      FLTADD     YES. MAKE THE ANGLE POSITIVE BY ADDING 360 DEG.
ANGRED1 DEC      FPACC2EX  MAKE THE CONSTANT IN FPACC2 90 DEGREES.
DEC      FPACC2EX
ANGRED2 JSR      FLTCMP     IS THE ANGLE LESS THAN 90 DEGREES ALREADY?
BLS      ANGRED3    YES. RETURN WITH QUAD COUNT.
JSR      FLTSSUB    NO. REDUCE ANGLE BY 90 DEGREES.
INC      0,Y      INCREMENT THE QUAD COUNT.
BRA      ANGRED2    GO SEE IF IT'S LESS THAN 90 NOW.
ANGRED3 LDAA     0,Y      GET THE QUAD COUNT.
CMPA     #1
BEQ      ANGRED4    WAS THE ORIGINAL ANGLE IN QUAD 1?
YES. COMPUTE TRIG FUNCTION AS IS.

```



```

        CMPA    #3          NO. WAS THE ORIGINAL ANGLE IN QUAD 3?
        BEQ    ANGRED4     YES. COMPUTE THE TRIG FUNCTION AS IF IN QUAD 1.
        LDAA   #$FF        NO. MUST COMPUTE THE TRIG FUNCTION OF THE 90'S
        STAA   MANTSGN1    COMPLIMENT ANGLE.
        JSR    FLTADD      ADD 90 DEGREES TO THE NEGATED ANGLE.
ANGRED4  DEC    FPACC2EX    MAKE THE ANGLE IN FPACC2 45 DEGREES.
        JSR    FLTCMP      IS THE ANGLE < 45 DEGREES?
        BLS    ANGRED5     YES. IT'S OK AS IT IS.
        INC    FPACC2EX    NO. MUST GET THE 90'S COMPLIMENT.
        LDAA   #$FF        MAKE FPACC1 NEGATIVE.
        STAA   MANTSGN1
        JSR    FLTADD      GET THE 90'S COMPLIMENT.
        INC    1,Y         SET THE FLAG.
ANGRED5  PULB           GET THE QUAD COUNT.
        PULA           GET THE COMPLIMENT FLAG.
        RTS            RETURN WITH THE QUAD COUNT & COMPLIMENT FLAG.

```

\*

\*

```

EXG1AND2 EQU    *
        LDD    FPACC1EX
        LDX    FPACC2EX
        STD    FPACC2EX
        STX    FPACC1EX
        LDD    FPACC1MN+1
        LDX    FPACC2MN+1
        STD    FPACC2MN+1
        STX    FPACC1MN+1
        LDAA   MANTSGN1
        LDAB   MANTSGN2
        STAA   MANTSGN2
        STAB   MANTSGN1
        RTS            RETURN.

```

\*

\*

```

SINFACT EQU    *
        FCB    $6E,$38,$EF,$1D      +(1/9!)
        FCB    $74,$D0,$0D,$01      -(1/7!)
        FCB    $7A,$08,$88,$89      +(1/5!)
        FCB    $7E,$AA,$AA,$AB      -(1/3!)

```

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COSFACT EQU    *
        FCB    $71,$50,$0D,$01      +(1/8!)
        FCB    $77,$B6,$0B,$61      -(1/6!)
        FCB    $7C,$2A,$AA,$AB      +(1/4!)
        FCB    $80,$80,$00,$00      -(1/2!)

```

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```

ONE     FCB    $81,$00,$00,$00      1.0
PI      FCB    $82,$49,$0F,$DB      3.1415927
THREE60 FCB    $89,$34,$00,$00      360.0

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FLOATING POINT TANGENT

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FLTTAN EQU    *
        JSR    PSHFPAC2    SAVE FPACC2 ON THE STACK.
        JSR    TFR1TO2    PUT A COPY OF THE ANGLE IN FPACC2.
        JSR    FLTCOS     GET COSINE OF THE ANGLE.
        JSR    EXG1AND2    PUT RESULT IN FPACC2 & PUT ANGLE IN FPACC1.
        JSR    FLTSIN     GET SIN OF THE ANGLE.
        JSR    FLTDIV     GET TANGENT OF ANGLE BY DOING SIN/COS.
        BCC    FLTTAN1    IF CARRY CLEAR, ANSWER OK.
        LDX    #MAXNUM    TANGENT OF 90 WAS ATTEMPTED. PUT LARGEST
        JSR    GETFPAC1    NUMBER IN FPACC1.
        LDAA   #TAN90ERR   GET ERROR CODE IN A.
FLTTAN1 JSR    PULFPAC2    RESTORE FPACC2.

```

```

RTS                                RETURN.
*
*
MAXNUM EQU *
FCB    $FE,$7F,$FF,$FF           LARGEST POSITIVE NUMBER WE CAN HAVE.
*
*
*****
*
*                                TRIG UTILITIES
*
*   The routines "DEG2RAD" and "RAD2DEG" are used to convert angles
*   from degrees-to-radians and radians-to-degrees respectively. The
*   routine "GETPI" will place the value of PI into FPACC1. This
*   routine should be used if the value of PI is needed in calculations
*   since it is accurate to the full 24-bits of the mantissa.
*
*****
*
DEG2RAD EQU *
      JSR PSHFPAC2             SAVE FPACC2.
      LDX #PIOV180           POINT TO CONVERSION CONSTANT PI/180.
DEG2RAD1 JSR GETFPAC2         PUT IT INTO FPACC2.
      JSR FLT MUL           CONVERT DEGREES TO RADIANS.
      JSR PULFPAC2         RESTORE FPACC2.
      RTS                   RETURN. (NOTE! DON'T REPLACE THE "JSR/RTS" WITH
*                               A "JMP" IT WILL NOT WORK.)
*
*
RAD2DEG EQU *
      JSR PSHFPAC2             SAVE FPACC2.
      LDX #C180OVPI         POINT TO CONVERSION CONSTANT 180/PI.
      BRA DEG2RAD1           GO DO CONVERSION & RETURN.
*
*
GETPI   EQU *
      LDX #PI                POINT TO CONSTANT "PI".
      JMP GETFPAC1          PUT IT IN FPACC1 AND RETURN.
*
*
PIOV180 EQU *
      FCB $7B,$0E,$FA,$35
*
C180OVPI EQU *
      FCB $86,$65,$2E,$E1
*
*
*****
*
*   The following two subroutines, PSHFPAC2 & PULFPAC2, push FPACC2
*   onto and pull FPACC2 off of the hardware stack respectively.
*   The number is stored in the "memory format".
*
*****
*
PSHFPAC2 EQU *
      PULX                   GET THE RETURN ADDRESS OFF OF THE STACK.
      PSHX                   ALLOCATE FOUR BYTES OF STACK SPACE.
      PSHX
      XGDX                   PUT THE RETURN ADDRESS IN D.
      TSX                    POINT TO THE STORAGE AREA.
      PS HB                   PUT THE RETURN ADDRESS BACK ON THE STACK.
      PSHA
      JMP PUTFPAC2           GO PUT FPACC2 ON THE STACK & RETURN.
*
*
PULFPAC2 EQU *
      TSX                    POINT TO THE RETURN ADDRESS.
      INX                    POINT TO THE SAVED NUMBER.

```

```

    INX
    JSR   GETFPAC2   RESTORE FPACC2.
    PULX   GET THE RETURN ADDRESS OFF THE STACK.
    INS    REMOVE THE NUMBER FROM THE STACK.
    INS
    INS
    INS
    JMP    0,X      RETURN.
*
*
*
*****
*
*                               GETFPACx SUBROUTINE
*
*   The GETFPAC1 and GETFPAC2 subroutines get a floating point number
*   stored in memory and put it into either FPACC1 or FPACC2 in a format
*   that is expected by all the floating point math routines. These
*   routines may easily be replaced to convert any binary floating point
*   format (i.e. IEEE format) to the format required by the math
*   routines. The "memory" format converted by these routines is shown
*   below:
*
*   31_____24 23 22_____0
*   exponent  s      mantissa
*
*   The exponent is biased by 128 to facilitate floating point
*   comparisons. The sign bit is 0 for positive numbers and 1
*   for negative numbers. The mantissa is stored in hidden bit
*   normalized format so that 24 bits of precision can be obtained.
*   Since a normalized floating point number always has its most
*   significant bit set, we can use the 24th bit to hold the mantissa
*   sign. This allows us to get 24 bits of precision in the mantissa
*   and store the entire number in just 4 bytes. The format required by
*   the math routines uses a separate byte for the sign, therefore each
*   floating point accumulator requires five bytes.
*
*****
*
*
GETFPAC1 EQU    *
    LDD    0,X      GET THE EXPONENT & HIGH BYTE OF THE MANTISSA,
    BEQ    GETFP12  IF NUMBER IS ZERO, SKIP SETTING THE MS BIT.
    CLR    MANTSGN1 SET UP FOR POSITIVE NUMBER.
    TSTB   IS NUMBER NEGATIVE?
    BPL    GETFP11  NO. LEAVE SIGN ALONE.
    COM    MANTSGN1 YES. SET SIGN TO NEGATIVE.
GETFP11  ORAB    #$80 RESTORE MOST SIGNIFICANT BIT IN MANTISSA.
GETFP12  STD    FPACC1EX PUT IN FPACC1.
    LDD    2,X      GET LOW 16-BITS OF THE MANTISSA.
    STD    FPACC1MN+1 PUT IN FPACC1.
    RTS    RETURN.
*
*
GETFPAC2 EQU    *
    LDD    0,X      GET THE EXPONENT & HIGH BYTE OF THE MANTISSA,
    BEQ    GETFP22  IF NUMBER IS 0, SKIP SETTING THE MS BIT.
    CLR    MANTSGN2 SET UP FOR POSITIVE NUMBER.
    TSTB   IS NUMBER NEGATIVE?
    BPL    GETFP21  NO. LEAVE SIGN ALONE.
    COM    MANTSGN2 YES. SET SIGN TO NEGATIVE.
GETFP21  ORAB    #$80 RESTORE MOST SIGNIFICANT BIT IN MANTISSA.
GETFP22  STD    FPACC2EX PUT IN FPACC1.
    LDD    2,X      GET LOW 16-BITS OF THE MANTISSA.
    STD    FPACC2MN+1 PUT IN FPACC1.
    RTS    RETURN.
*
*
*
*****
*
*                               PUTFPACx SUBROUTINE
*
*

```

```

*           These two subroutines perform to opposite function of GETFPAC1 and *
*           GETFPAC2. Again, these routines are used to convert from the *
*           internal format used by the floating point package to a "memory" *
*           format. See the GETFPAC1 and GETFPAC2, documentation for a *
*           description of the "memory" format. *
*
*****
*
*
PUTFPAC1 EQU      *
                LDD  FPACC1EX      GET FPACC1 EXPONENT & UPPER 8 BITS OF MANT.
                TST  MANTSGN1      IS THE NUMBER NEGATIVE?
                BMI  PUTFP11       YES. LEAVE THE M.S. BIT SET.
                ANDB #\$7F         NO. CLEAR THE M.S. BIT.
PUTFP11  STD     0,X              SAVE IT IN MEMORY
                LDD  FPACC1MN+1    GET L.S. 16 BITS OF THE MANTISSA.
                STD  2,X
                RTS
*
*
PUTFPAC2 EQU      *
                LDD  FPACC2EX      GET FPACC1 EXPONENT & UPPER 8 BITS OF MANT.
                TST  MANTSGN2      IS THE NUMBER NEGATIVE?
                BMI  PUTFP21       YES. LEAVE THE M.S. BIT SET.
                ANDB #\$7F         NO. CLEAR THE M.S. BIT.
PUTFP21  STD     0,X              SAVE IT IN MEMORY
                LDD  FPACC2MN+1    GET L.S. 16 BITS OF THE MANTISSA.
                STD  2,X
                RTS
*

```

## Appendix D – Loading and Firing Code

This is the most recent version of my code. It is not complete of functional, and I am constantly changing it. I will replace this with the final version when I have complete it.

```
*****
*      My Constants and Variables      *
*****

DISTANCE      EQU    $0230
V_GET_X       EQU    $01
V_GET_Y       EQU    $02
V_GET_THETA   EQU    $03
V_START_MOUSE EQU    $04
V_STOP_MOUSE  EQU    $05
V_RESET_M_CNT EQU    $06
V_RESET_ANGLE EQU    $07
V_COMP_DIST   EQU    $08

BASE          EQU    $1000
STACK         EQU    $7000
PORTA         EQU    $00
PIOC          EQU    $02
PORTC         EQU    $03
PORTB         EQU    $04
PORTCL        EQU    $05
DDRC          EQU    $07
PORTD         EQU    $08
DDRD          EQU    $09
PORTE         EQU    $0A
CFORC         EQU    $0B
OC1M          EQU    $0C
OC1D          EQU    $0D
TCNT          EQU    $0E
TIC1          EQU    $10
TIC2          EQU    $12
TIC3          EQU    $14
TOC1          EQU    $16
TOC2          EQU    $18
TOC3          EQU    $1A
TOC4          EQU    $1C
TI4/O5        EQU    $1E
TOC5          EQU    $1E
TCTL1         EQU    $20
TCTL2         EQU    $21
TMSK1         EQU    $22
TFLG1         EQU    $23
TMSK2         EQU    $24
TFLG2         EQU    $25
PACTL         EQU    $26
PACNT         EQU    $27
SPCR          EQU    $28
SPSR          EQU    $29
SPDR          EQU    $2A
```

```

BAUD      EQU    $2B
SCCR1     EQU    $2C
SCCR2     EQU    $2D
SCSR      EQU    $2E
SCDR      EQU    $2F
ADCTL     EQU    $30
ADR1      EQU    $31
ADR2      EQU    $32
ADR3      EQU    $33
ADR4      EQU    $34
BPROT     EQU    $35
EPROG     EQU    $36
OPTION    EQU    $39
COPRST    EQU    $3A
PPROG     EQU    $3B
HPRIO     EQU    $3C
INIT      EQU    $3D
TEST      EQU    $3E
CONFIG    EQU    $3F

PE1      EQU    %00000001    ;Value for ADCTL:
PE2      EQU    %00000010

BIT0      EQU    %00000001
BIT1      EQU    %00000010
BIT2      EQU    %00000100
BIT3      EQU    %00001000
BIT4      EQU    %00010000
BIT5      EQU    %00100000
BIT6      EQU    %01000000
BIT7      EQU    %10000000

BIT543    EQU    %00111000

* Interrupt Vectors
    ORG    $00D3
    JMP    handle_oc5
    JMP    handle_oc4
    JMP    handle_oc3
    JMP    handle_oc2
    JMP    handle_oc1

    ORG    $8000
INT
    lds    #$01ff
    clra
    staa   TMSK2,x
    ldaa   #%11111000        ;the 1's correspond to OC1-5
    staa   TFLG1,x
    staa   TMSK1,x
    bset   TCTL1,x %01010101 ; toggle at interrupt, OC2-4
    ldaa   #$80              ; special OC1 setup
    staa   PACTL,x
    staa   OC1M,x
    cli
    LDX    #$1000

```

```

        LDAA  #%10000000    ; Bit 7 (ADPU) of OPTION
        STAA  OPTION,X      ; ..turn on A/D system

* Wait 100 microsec = 200 E-cycles for Charge Pump to Stabilize
        LDAA  #40           ; 2 E cycles
WAIT1   DECA           ; 2 E cycles
        BNE   WAIT1        ; 3 E cycles [(2+3)*40=200 E's]

        rts

        ORG   $8500
LOAD    LDD   #$14B0
        STD   $2
        LDAB  $D7

        LDAA  #PE1
        JSR   SAMPLE
        CBA
        BGT   LOAD
        BEQ   DONE1
        LDD   #$04B0
        STD   $2
        BRA   LOAD
DONE1   LDD   #$0BA0
        STD   $2
        RTS

        ORG   $9000
ARM     LDD   #$14B0
        STD   $2
        LDAB  $F7

        LDAA  #PE1
        JSR   SAMPLE
        CBA
        BGT   ARM
        BEQ   DONE2
        LDD   #$04B0
        STD   $2
        BRA   ARM
DONE2   LDD   #$0BA0
        STD   $2

        LDAA  $FF
        STAA  $7000
        RTS

        ORG   $9500
LOCK    LDD   #$14A0
        STD   $4
        LDAA  #106
LOCK1   NOP
        DECA
        BNE   LOCK1

        LDD   #$0BA0
        STD   $04

```

```

        LDD    #$04B0
        STD    $02
        RTS

FIRE    LDD    #$04A0
        STD    $4
        LDAA   #106
FIRE1   NOP
        DECA
        BNE   FIRE1

        LDD    #$0BA0
        STD    $04
        RTS

SAMPLE  LDX    #1000
        STAA  ADCTL,X          ;    PE1=BIT0

        LDAA  #6              ; 2 E cycles
WAIT2   DECA              ; 2 E cycles
        BNE   WAIT2          ; 3 E cycles (2+3)*6=30 E's
        LDAA  ADR1,X          ; Get new data

        RTS

handle_oc5:
        ldx   #$1000          ;required for bclr
        bclr  TFLG1,x %11110111
        ldaa  0,x            ;find level of PWM now
        anda  #%00001000
        beq   oc5pwmdown     ;level is down
        ldd   $08            ;load 'on' period from low mem
        bra   oc5pwmend
oc5pwmdown
        ldd   #28960          ;load constant low period
oc5pwmend
        addd  TOC5,x          ;add loaded period (hi or low)
        std   TOC5,x          ;set next inerrupt
        rti                   ;all done

handle_oc4:
        ldx   #$1000          ;a slightly different routine is needed
        bclr  TFLG1,x %11101111 ;for each line. (different masks)
        ldaa  0,x
        anda  #%00010000
        beq   oc4pwmdown
        ldd   $06
        bra   oc4pwmend
oc4pwmdown
        ldd   #28960
oc4pwmend
        addd  TOC4,x
        std   TOC4,x
        rti

handle_oc3:
        ldx   #$1000
        bclr  TFLG1,x %11011111

```



```

        ldaa 0,x
        anda #%00100000
        beq  oc3pwmdown
        ldd  $04
        bra  oc3pwmend
oc3pwmdown
        ldd  #28960
oc3pwmend
        addd TOC3,x
        std  TOC3,x
        rti
handle_oc2:
        ldx  #$1000
        bclr TFLG1,x %10111111
        ldaa 0,x
        anda #%01000000
        beq  oc2pwmdown
        ldd  $02
        bra  oc2pwmend
oc2pwmdown
        ldd  #28960
oc2pwmend
        addd TOC2,x
        std  TOC2,x
        rti
handle_oc1:
        ldx  #$1000
        bclr TFLG1,x %01111111
        ldaa 0,x
        anda #%10000000
        beq  oc1pwmdown
        ldd  $00
        bra  oc1pwmend
oc1pwmdown
        ldd  #28960
oc1pwmend
        addd TOC1,x
        std  TOC1,x
        ldaa OC1D,x
        eora #$80
        staa OC1D,x
        rti

```