



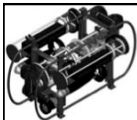
IMDL Software Series

Atmel AVR Xmega Code using GPIO from the Atmel ASF for the ADC on DAQ Boards

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IMDL Software Series ADC

The Analog to Digital Converters (ADC) is used to sample and digitize analog signals. These devices are simple to communicate with and are quicker to set up than a USART.

Typical Applications:

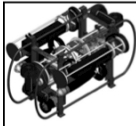
- Audio Input
- Checking battery voltage
- Sensor - i.e., IR range finder

XMega A1 devices have two ADCs. These two modules can be operated simultaneously, individually or synchronized.

In the DAQ board they convert a 0 to 5v range into a 12-bit range (0 to 4095), about a $\sim 0.025\%$ increment, e.g., 0 = 0v; 0xFFF=4095 \approx 5v; 2047 \approx 2.5v; 511 \approx 0.625v, etc.

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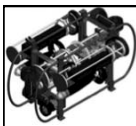
IMDL Software Series ADC

28.1 Features

- 12-bit resolution
- Up to two million samples per second
 - Two inputs can be sampled simultaneously using ADC and 1x gain stage
 - Four inputs can be sampled within 1.5µs
 - Down to 2.5µs conversion time with 8-bit resolution
 - Down to 3.5µs conversion time with 12-bit resolution
- Differential and single-ended input
 - Up to 16 single-ended inputs
 - 16x4 differential inputs without gain
 - 8x4 differential input with gain
- Built-in differential gain stage
 - 1/2x, 1x, 2x, 4x, 8x, 16x, 32x, and 64x gain options
- Single, continuous and scan conversion options
- Four internal inputs
 - Internal temperature sensor
 - DAC output
 - V_{CC} voltage divided by 10
 - 1.1V bandgap voltage
- Four conversion channels with individual input control and result registers
 - Enable four parallel configurations and results
- Internal and external reference options
- Compare function for accurate monitoring of user defined thresholds
- Optional event triggered conversion for accurate timing
- Optional DMA transfer of conversion results
- Optional interrupt/event on compare result

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IMDL Software Series ADC

Figure 28-1. ADC overview.

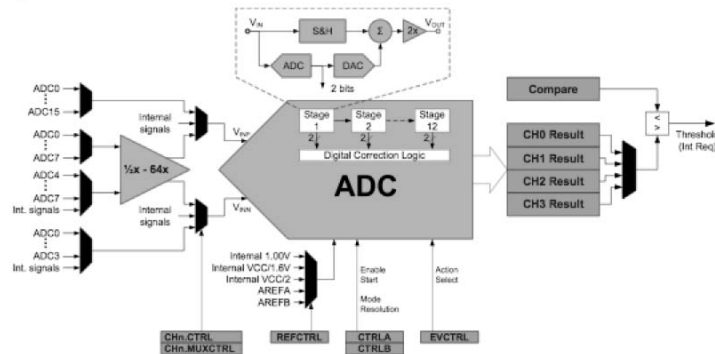


Figure 28-5. Single-ended measurement in unsigned mode.

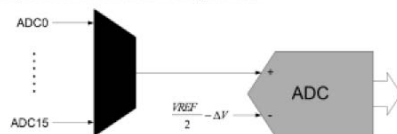
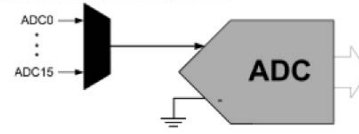
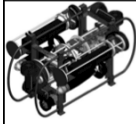


Figure 28-4. Single-ended measurement in signed mode.



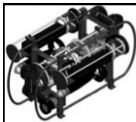
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IMDL Software Series ADC

Before a conversion is started, the desired input source must be selected for one or more ADC channels. An ADC conversion for a ADC channel can either be started by the application software writing to the start conversion bit for the ADC channel, or from any of the events in the Event System. It is possible to write the start conversion bit for several ADC channels at the same time, or to use one event to trigger conversions on several ADC channels at the same time. This makes it possible to scan several or all channels from one event. The scan will start from the lowest channel number.



IMDL Software Series ADC

- The ADC is enabled by setting the ADC Enable bit0 in the CTRLA control Register.

Example:

```
ADCA_CTRLA |= 0x01; //Enable ADCA
ADCA_CTRLA |= 0x04; //Start Conversion on ADCA Chn 0
```

CTRLA – Control register A

Bit	7	6	5	4	3	2	1	0
+Qx00	DMASEL[1:0]		CHSTART[3:0]			FLUSH	ENABLE	
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Initial Value	0	0	0	0	0	0	0	0

- **Bit 5:2 – CHSTART[3:0]: Channel Start Single Conversion**
Setting any of these bits will start a conversion on the corresponding ADC channel. Setting several bits at the same time will start conversions on all selected ADC channels, starting with the channel with the lowest number. These bits are cleared by hardware when the conversion has started.
- **Bit 0 – ENABLE: Enable**
Setting this bit enables the ADC.



IMDL Software Series ADC

- The ADC 12-bit result is placed in the CHnRES Registers, CHnRESH and CHnRESL. By default, the result is presented right adjusted, but can optionally be presented left adjusted.
Example:

`ADCA_CTRLB = 0x00; //12bit, right adjusted`

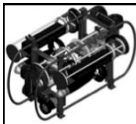
CTRLB – ADC Control register B

Bit	7	6	5	4	3	2	1	0
+0x01	IMPMODE		CURRLIMIT[1:0]		CONVMODE	FREERUN	RESOLUTION[1:0]	
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R
Initial Value	0	0	0	0	0	0	0	0

- Bit 3 – FREERUN: Free Running Mode**
When the bit is set to one, the ADC is in free running mode and the ADC channels defined in the EVCTRL register are swept repeatedly.
- Bit 2:1 – RESOLUTION[1:0]: Conversion Result Resolution**
These bits define whether the ADC completes the conversion at 12- or 8-bit result resolution. They also define whether the 12-bit result is left or right adjusted within the 16-bit result registers. See Table 28-4 on page 352 for possible settings.

Table 28-4. ADC conversion result resolution.

RESOLUTION[1:0]	Group configuration	Description
00	12BIT	12-bit result, right adjusted
01		Reserved
10	8BIT	8-bit result, right adjusted
11	LEFT12BIT	12-bit result, left adjusted



IMDL Software Series ADC

- The ADC reference is selected in the REFCTRL.
Example: On my Epiphany DIY

`ADCA_REFCTRL = 0x10; //Set to Vref = 5v on ADCA`

`//Set to Vref = Vcc/1.6 ≈ 2.0v on ADCB`

REFCTRL – Reference Control register

Bit	7	6	5	4	3	2	1	0
+0x02	–	REFSEL[2:0]			–	–	BANDGAP	TEMPREF
Read/Write	R	R/W	R/W	R/W	R	R	R/W	R/W
Initial Value	0	0	0	0	0	0	0	0

- Bit 7 – Reserved**
This bit is unused and reserved for future use. For compatibility with future devices, always write this bit to zero when this register is written.
- Bits 6:4 – REFSEL[2:0]: Reference Selection**
These bits selects the reference for the ADC according to Table 28-5 on page 353.

Table 28-5. ADC reference selection.

REFSEL[2:0]	Group configuration	Description
000	INT1V	10/11 of bandgap (1.0V)
001	INTVCC	$V_{CC}/1.6$
010	AREFA	External reference from AREF pin on PORT A
011	AREFB	External reference from AREF pin on PORT B
100	INTVCC2	$V_{CC}/2$
101 - 111		Reserved



IMDL Software Series ADC

- Set Pre-Scaler Configuration. Example:
ADCA_PRESCALER = 0x03; // sets Prescaler to DIV32

PRESCALER – Clock Prescaler register

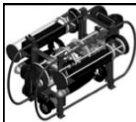
Bit	7	6	5	4	3	2	1	0
+0x04	PRESCALER[2:0]							
Read/Write	R	R	R	R	R	R/W	R/W	R/W
Initial Value	0	0	0	0	0	0	0	0

• **Bit 2:0 – PRESCALER[2:0]: Prescaler Configuration**

These bits define the ADC clock relative to the peripheral clock according to Table 28-9 on page 355.

Table 28-9. ADC prescaler settings.

PRESCALER[2:0]	Group configuration	Peripheral clock division factor
000	DIV4	4
001	DIV8	8
010	DIV16	16
011	DIV32	32
100	DIV64	64
101	DIV128	128
110	DIV256	256
111	DIV512	512



IMDL Software Series ADC

- To start single-ended conversions we use the CTRL register. Example:
ADCA_CH0_CTRL = 0x01; //set to single-ended

CTRL – Channel Control register

Bit	7	6	5	4	3	2	1	0
+0x00	START				GAIN[2:0]		INPUTMODE[1:0]	
Read/Write	R/W	R	R	R/W	R/W	R/W	R/W	R/W
Initial Value	0	0	0	0	0	0	0	0

• **Bit 7 – START: START Conversion on Channel**

Setting this bit will start a conversion on the channel. The bit is cleared by hardware when the conversion has started. Setting this bit when it already is set will have no effect. Writing or reading this bit is equivalent to writing the CH[3:0]START bits in "CTRLA – Control register A" on page 351.

Table 28-11. Channel input modes, CONVMODE=0 (unsigned mode).

INPUTMODE[1:0]	Group configuration	Description
00	INTERNAL	Internal positive input signal
01	SINGLEENDED	Single-ended positive input signal
10		Reserved
11		Reserved



IMDL Software Series ADC

- The MUX register defines the input source for the channel. Example:

```
ADCA_CH0_MUXCTRL = 0x08; //default to Channel 1
```

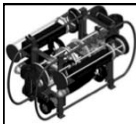
MUXCTRL – ADC Channel MUX Control registers

The MUXCTRL register defines the input source for the channel.

Bit	7	6	5	4	3	2	1	0
+0x01	-			MUXPOS[3:0]			MUXNEG[2:0]	
Read/Write	R	R/W	R/W	R/W	R/W	R	R/W	R/W
Initial Value	0	0	0	0	0	0	0	0

Table 28-14. ADC MUXPOS configuration when INPUTMODE[1:0] = 01 (single-ended) or INPUTMODE[1:0] = 10 (differential) is used.

MUXPOS[3:0]	Group configuration	Description
0000	PIN0	ADC0 pin
0001	PIN1	ADC1 pin
0010	PIN2	ADC2 pin
0011	PIN3	ADC3 pin
0100	PIN4	ADC4 pin
0101	PIN5	ADC5 pin
0110	PIN6	ADC6 pin
0111	PIN7	ADC7 pin



IMDL Software Series ADC

- Conversions are controlled with the INTCTRL. Example:

```
ADCA_CH0_INTCTRL = 0x00; //set flag at conversion complete. Disable interrupt
```

INTCTRL – Channel Interrupt Control registers

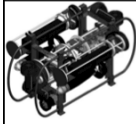
Bit	7	6	5	4	3	2	1	0
+0x02	-			INTMODE[1:0]			INTLVL[1:0]	
Read/Write	R	R	R	R	R/W	R/W	R/W	R/W
Initial Value	0	0	0	0	0	0	0	0

- Bit 3:2 – INTMODE: Interrupt Mode**
These bits select the interrupt mode for the channel according to Table 28-18.

Table 28-18. ADC channel select.

INTMODE[1:0]	Group configuration	Interrupt mode
00	COMPLETE	Conversion complete
01	BELOW	Compare result below threshold
10		Reserved
11	ABOVE	Compare result above threshold

- Bits 1:0 – INTLVL[1:0]: Interrupt Priority Level and Enable**
These bits enable the ADC channel interrupt and select the interrupt level, as described in "Interrupts and Programmable Multilevel Interrupt Controller" on page 130. The enabled interrupt will be triggered for conditions when the IF bit in the INTFLAGS register is set.



IMDL Software Series ADC

- Conversions flags are in the INTFLAGS.

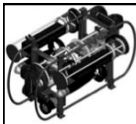
Example:

```
// wait for conversion to complete
while ((ADCA_CH0_INTFLAGS & 0x01) != 0x01);
```

INTFLAGS – ADC Channel Interrupt Flag registers

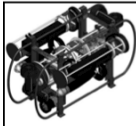
Bit	7	6	5	4	3	2	1	0
*0x03	--	--	--	--	--	--	--	IF
Read/Write	R	R	R	R	R	R	R	R/W
Initial Value	0	0	0	0	0	0	0	0

- **Bit 7:1 – Reserved**
These bits are unused and reserved for future use. For compatibility with future devices, always write these bits to zero when this register is written.
- **Bit 0 – IF: Channel Interrupt Flag**
The interrupt flag is set when the ADC conversion is complete. If the channel is configured for compare mode, the flag will be set if the compare condition is met. IF is automatically cleared when the ADC channel interrupt vector is executed. The bit can also be cleared by writing a one to the bit location.



IMDL Software Series ADC - Epiphany

```
* AAA Utilc - Notepad2 (Administrator)
File Edit View Settings ?
1 /*****
2 * Xmega *
3 *****/
4 void xmegaInit(void) {           // xmegaInit: initialize Xmega CPU to 32MHz
5     CCP      = 0x08;           // configuration change Protection: IOREG (0x08)
6     CLK_PSCTRL = 0x00;         // System Clock Prescaler Reg All prescalers No Division
7     OSC_CTRL  = 0x02;         // Bit 1- RC32MEN: Setup 32 MHz Internal CPU RC Oscillator Enable
8     while ((OSC_STATUS & 0x02) == 0); // wait for Bit 1 - RC32MRDY: 32 MHz Internal RC Oscillator Ready
9     CCP      = 0x08;           // configuration change Protection: IOREG (0x08)
10    CLK_CTRL  = 0x01;         // Bit 2:0 - SCLKSEL[2:0]: System Clock Selection
11    // End xmegaInit           // 001 : RC32MHZ  32MHz Internal RC oscillator
12
13 /*****
14 * ADCA *
15 *****/
16 void ADCAInit(void) {          // ADCAInit: Initialize ADC on Porta pins
17     ADCA_CTRLB = 0x00;         // 12bit, right adjusted
18     ADCA_REFCTRL = 0x10;       // set to Vref = Vcc/1.6 = 2.0V (approx) In Tim's board 5v
19     ADCA_CH0_CTRL = 0x01;     // set to single-ended
20     ADCA_CH0_INTCTRL = 0x00;  // set flag at conversion complete. Disable interrupt
21     ADCA_CH0_MUXCTRL = 0x08;  // default set to channel ADCA1 Porta Pin 1
22     ADCA_PRESCALER = 0x03;    // sets ADC prescaler to DIV32
23     ADCA_CTRLA |= 0x01;       // Enable ADCA
24 } // End ADCAInit
25
26 int analog(int channel) {      // analog[channel]{ADCA Porta-0:7} Read the Porta ADC channel
27     ADCA_CH0_MUXCTRL = channel*8; // Set to ADCAn Porta pin n where n=channel is <-7-0>
28     ADCA_CTRLA |= 0x04;       // Start conversion on ADCA channel 0
29     while ((ADCA_CH0_INTFLAGS & 0x01) != 0x01); // wait for conversion to complete
30     _delay_ms(5);             // wait for result to stabilize [may not be needed]
31     int value = ADCA_CH0_RES;  // grab result
32     return value;             // return result
33 } // End analog(channel)
34
```

IMDL Software Series ADC - DAQ

```

void main() {
  ADC_Init();
  ADC_Calib = ReadCalibrationByte( offsetof(INM_PROD_SIGNATURES_1, ADCALIB) );
  ADC_Calib = ReadCalibrationByte( offsetof(INM_PROD_SIGNATURES_1, ADCALIB) );
  //delay of analog startup
  MCU_ANASMIT = MCU_STARTUP0V1A1_bm | MCU_STARTUP0V1A1_bm;

  //select the 2.5V external reference
  //ADCA_REFCTRL = (0x03<<4); // 0x 0011 0000 = 0x10 /* External reference on PORT B */
  ADCA_REFCTRL = ADC_REFSEL_AREFB_gc;

  //ADC prescaler selection
  //ADCA_PRESCALER = (0x05<<0); // 0x 0000 0101 = 0x05 /* Divide clock by 128 */
  ADCA_PRESCALER = ADC_PRESCALER_DIV128_gc;

  //setup the ADC configuration
  //ADCA_CTRLB =
  ADCA_CTRLB = 0x08 | (0x00<<5) | 0x18 | 0x08 | (0x00<<1); // 0x 1001 1000 = 0x08
  ADCA_CTRLB |=
  ADC_SMPMODE_bm | //high impedance enable, since the board uses op-amps for the front end
  ADC_COMPRESM_DISABLE_gc | //inhibit the current limit in order to max out the ADC speed
  ADC_COMPMODE_bm | //sets up the conversion for signed mode
  ADC_FREERUN_bm | //sets up the adc to collect data autonomously
  ADC_RESOLUTEM_12BIT_gc | //sets adc to have 12 bit resolution with right adjustment (LSB)

  //tell the ADC to sleep all channels 0-3 automatically
  //ADCA_EVCTRL = (0x03<<0); // 0x 1100 0000 = 0xC0 /* ADC Channel 0,1,2,3 */
  ADCA_EVCTRL = ADC_SMEEP_0123_gc;

  //*****Channel 0 setup*****
  //*****Binary gain and input mode selection*****
  //ADCA_CH0_CTRL = (0x02<<2) | (0x03<<0); // 0x 0000 1011 = 0xB0
  ADCA_CH0_CTRL = ADC_CH_GAIN_0x_gc | ADC_CH_INPMODE_DIFFGAIN_gc;
  //ADCA_CH1_CTRL = (0x02<<2) | (0x03<<0); // 0x 0000 1011 = 0xB0
  ADCA_CH1_CTRL = ADC_CH_GAIN_0x_gc | ADC_CH_INPMODE_DIFFGAIN_gc;
  //ADCA_CH2_CTRL = (0x02<<2) | (0x03<<0); // 0x 0000 1011 = 0xB0
  ADCA_CH2_CTRL = ADC_CH_GAIN_0x_gc | ADC_CH_INPMODE_DIFFGAIN_gc;
  //ADCA_CH3_CTRL = (0x02<<2) | (0x03<<0); // 0x 0000 1011 = 0xB0
  ADCA_CH3_CTRL = ADC_CH_GAIN_0x_gc | ADC_CH_INPMODE_DIFFGAIN_gc;

  // mux positions
  //ADCA_CH0_MUXCTRL = (0x03<<3) | (0x05<<0); // 0x 0001 1000 = 0x18
  ADCA_CH0_MUXCTRL = ADC_CH_MUXPSL_P7M0_gc | ADC_CH_MUXSEL_P7M0_gc;
  //ADCA_CH1_MUXCTRL = (0x03<<3) | (0x05<<0); // 0x 0001 1000 = 0x18
  ADCA_CH1_MUXCTRL = ADC_CH_MUXPSL_P7M0_gc | ADC_CH_MUXSEL_P7M0_gc;
  //ADCA_CH2_MUXCTRL = (0x03<<3) | (0x05<<0); // 0x 0001 1000 = 0x18
  ADCA_CH2_MUXCTRL = ADC_CH_MUXPSL_P7M0_gc | ADC_CH_MUXSEL_P7M0_gc;
  //ADCA_CH3_MUXCTRL = (0x03<<3) | (0x05<<0); // 0x 0001 1000 = 0x18
  ADCA_CH3_MUXCTRL = ADC_CH_MUXPSL_P7M0_gc | ADC_CH_MUXSEL_P7M0_gc;

  //ADCA_CH0_INTCTRL = (0x00<<2) | (1<<0); // 0x 0000 0001 = 0x01
  ADCA_CH0_INTCTRL = ADC_CH_INTMODE_COMPLETE_gc | ADC_CH_INTLVLS_bm;
  //ADCA_CH1_INTCTRL = (0x00<<2) | (1<<0); // 0x 0000 0001 = 0x01
  ADCA_CH1_INTCTRL = ADC_CH_INTMODE_COMPLETE_gc | ADC_CH_INTLVLS_bm;
  //ADCA_CH2_INTCTRL = (0x00<<2) | (1<<0); // 0x 0000 0001 = 0x01
  ADCA_CH2_INTCTRL = ADC_CH_INTMODE_COMPLETE_gc | ADC_CH_INTLVLS_bm;
  //ADCA_CH3_INTCTRL = (0x00<<2) | (1<<0); // 0x 0000 0001 = 0x01
  ADCA_CH3_INTCTRL = ADC_CH_INTMODE_COMPLETE_gc | ADC_CH_INTLVLS_bm;

  //ADCA_CH0_CTRL |= 0x08
  ADCA_CH0_CTRL |= ADC_CH_START_bm;
  //ADCA_CH1_CTRL |= 0x08
  ADCA_CH1_CTRL |= ADC_CH_START_bm;
  //ADCA_CH2_CTRL |= 0x08
  ADCA_CH2_CTRL |= ADC_CH_START_bm;
  //ADCA_CH3_CTRL |= 0x08
  ADCA_CH3_CTRL |= ADC_CH_START_bm;
  ADCA_CTRLA |= 0x01;
  ADCA_CTRLA |= ADC_ENABLE_bm;
  //set the appropriate interrupt levels at the global scope
  //PMIC_CTRL |= (0x01 | 0x08); // 0x01
  PMIC_CTRL |= PMIC_INTLVLS_bm | PMIC_INTEN_bm;
}

```



IMDL Software Series ADC

- The next example uses the ADC to sample a Cds cell and turn on/off the debug LED on PC1 in the main loop in Tim’s DAQ Board.

See project DAQ_GPIO_ADC

- If you wish to use Tim’s USART functions, then import `uart.c` and `uart.h` from Tim’s Software

See project DAQ_GPIO_ADC

Change the include in `main.c` to `<uart.h>`



IMDL Software Series Arduino ADC

- The example uses the ADC functions in the Arduino MEGA2560 Board to blink internal/ external LEDs and uses the serial port to display data and control the LEDs after blinking the set a few times. Serial input j & k alternate the two external LEDs on pins 12 & 11 {on, off} and {off, on} respectively. Analog input A0 is connected to a Cds cell that controls the internal DBLED
- See Arduino Sketch: IMDL_ADC_Serial_External_LED



IMDL Software Series

```
1 /*
2  EEL-5666 Example 3: Use of Digital Output Pins
3  Turn on/off External LEDs connected to Pins 11 & 12
4  alternatively and the internal LED on Pin 13 on/off.
5  Add a delay in each state of 1/2 sec. Use serial input
6  to control the LEDs. (1,0) for internal LED (j,K) for
7  external LEDs. Read Cds cell on Analog A0 and control
8  the internal LED.
9  Arroyo January 18, 2016
10 */
11
12
13 int extLED1 = 11; // External LED connected to digital pin 11
14 int extLED2 = 12; // External LED connected to digital pin 12
15 int intLED = 13; // Internal LED connected to digital pin 13
16
17 void setup() {
18   pinMode(extLED1, OUTPUT); // sets digital pin 12 as output
19   pinMode(extLED2, OUTPUT); // sets digital pin 12 as output
20   pinMode(intLED, OUTPUT); // sets digital pin 13 as output
21   Serial.begin(57600); // connect to the serial port
22 }
23
24 int rcvData=0, count=0, ambient, a1;
25 void loop() {
26   if (count < 1) {
27     Serial.println("Arduino MEGA2560 Example");
28     Serial.println("Cds Cell connected on Analog A0");
29     Serial.println("Control the internal LED on pin 13");
30     ambient = analogRead(A0);
31     Serial.print("Ambient: ");
32     Serial.println(ambient);
33
34     for (int j=0; j<5; j++){
35       Serial.print("j= ");
36       Serial.println(j);
37       digitalWrite(13, HIGH); // set the internal LED on
```



IMDL Software Series

```
38     digitalWrite(12, LOW);    // set the external LED1 off
39     digitalWrite(11, HIGH);  // set the external LED2 on
40     delay(500);              // wait for a 1/2 second
41     digitalWrite(13, LOW);   // set the internal LED off
42     digitalWrite(12, HIGH);  // set the external LED on
43     digitalWrite(11, LOW);   // set the external LED off
44     delay(500);              // wait for a 1/2 second
45 }
46 digitalWrite(13, HIGH);    // set the internal LED on
47 digitalWrite(12, HIGH);    // set the external LED1 on
48 digitalWrite(11, HIGH);    // set the external LED2 on
49 }
50 count=1;
51 Serial.print("Ambient: ");
52 Serial.print(ambient);
53 Serial.print(" A1: ");
54 a1 = analogRead(A0);
55 if (a1 > 1.1*ambient) digitalWrite(13, LOW); // turn off DBLED
56 else digitalWrite(13, HIGH); // else turn on DBLED
57 Serial.println(a1);
58 delay(100);
59
60 // blink data only when you receive data:
61 if (Serial.available() > 0) {
62 // read the incoming byte:
63   rcvData = Serial.read();
64 // say what you got:
65   Serial.print("I received: ");
66   Serial.write(rcvData);
67   Serial.println();
68   if (rcvData == 'i') digitalWrite(13, HIGH); // internal LED on
69   else if (rcvData == 'o') digitalWrite(13, LOW); // internal LED off
70   else if (rcvData == 'j') (digitalWrite(12,LOW); digitalWrite(11,HIGH));
71   else if (rcvData == 'k') (digitalWrite(12,HIGH); digitalWrite(11,LOW));
72 }
73 }
74 }
```

Normal text file length: 2739 lines: 74 Ln: 28 Col: 55 Sel: 3|0 U



IMDL Software Series

The End!